Optimization in practice

From long to short, from planning to operation of (power) grids



analytical. quantitative. tech.

Berlin, 27.09.2024

Short Profile



Short Profile



Working at d-fine allows me to continue pursuing my academic passion of mathematical optimization and putting my expertise into practice by tackling real-world problems.

d-fine is a European consultancy focusing on analytical, quantitative and technological endeavours



Together with our clients, we drive strategies, develop business designs and implement tailored IT solutions. A collaborative and trustworthy relationship is important to us.

Our industry experience and competences



implementation

d-fine project examples

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OPTIMIZATION IN PRACTICE

01 Project examples: Energy grid investments

PROJECT EXAMPLE: ENERGY GRID INVESTMENTS

01.01 Introduction

Energy transition – one of the greatest challenges of the 21st century⁰¹



Sector-linked view of the energy industry for optimal planning of future investments



01 Renewable energy (renewables) includes the energy sources wind, PV, etc.. 02 Oils includes crude oil as well as naphtha (chemical industry) and kerosene (aviation) from Fischer-Tropsch synthesis 03 Demand-side management (DSM) covers the household, industry & transport sectors as well as vehicle-2-grid (V2G).

PyPSA-Eur – An Open-Source Energy System Model



- Fully equipped with data, solver, configuration, etc.
- Transparent development (GitHub)
- Over 47 users of the PyPSA framework in science and industry (e.g. Shell, TransnetBW, TUB, KIT, ...)



... is used for modelling all relevant energy sectors.⁰¹

01 https://github.com/PyPSA/pypsa-eur

Why Linear Programming?



60 Nodes 10 Time steps, i.e. $\Delta t = 876h$ CPU time Optimisation: 5,6s

Original problem h	las:			
259022 rows	126645	cols	604820	elements
Presolved problem	has:			
82580 rows	104394	cols	386517	elements

60 Nodes 730 Time steps, i.e. $\Delta t = 12h$

CPU time Optimisation: 4h				Mio.	
Original problem has:					
20609875 rows	9856913	cols	48	963690	elements
Presolved problem	has:				
5843258 nows	8288401	cols	30	998733	elements

60 Nodes 2190 Time steps, i.e. $\Delta t = 4h$

or o time optimisation. Tor	1	Mio.		
Original problem has:				
60802113 rows 29049220	cols 143	934817	elements	
Presolved problem has:				
16662218 rows 23584462	cols 89	226090	elements	

Energy system models are "extreme-scale" and therefore modeling with non-linearities is only permissible for smaller sections (temporal or spatial).

PROJECT EXAMPLE: ENERGY GRID INVESTMENTS

01.02 PyPSA: Power System Analysis

Example Network Optimization: Minimum-cost flow problem



Given a network consisting of a directed Graph G = (V, E) with node supply/demand b_i for each node $i \in V$, costs $c_{i,j} \in \mathbb{R}$ and capacities $u_{i,j} \in \mathbb{R}$ for each edge $(i, j) \in E$. Find the cheapest possible way to meet the demand in the network.⁰¹

Assumption: The demand equals the given supply

$$\sum_{i\in V}b_i=0$$

Objective function

$$\min\sum_{(i,j)\in E}c_{i,j}x_{i,j}$$

Flow balancing constraints

$$\sum_{j:(i,j)\in V} x_{i,j} - \sum_{j:(j,i)\in V} x_{j,i} = b_i \text{ for every } i \in V$$

Capacity constraints

$$0 \leq x_{i,j} \leq u_{i,j}$$
 for all $(i, j) \in B$

Real-world application of network optimization:

- communication systems
- manufacturing systems
- transportation systems
- water systems
- energy systems

Remarks

- ≤ 0 , demand at node $j \in V$ > 0, supply at node $j \in V$
- costs for edge $(i, j) \in E$ Cii
- flow over edge $(i, j) \in E$ $x_{i,i}$
- $u_{i,i}$ capacity of edge $(i, j) \in E$

Note:

$$x_{i,j} = -x_{j,i} \forall (i,j) \in E$$





01 https://ocw.mit.edu/courses/sloan-school-of-management/15-082j-network-optimization-fall-2010/lecturenotes/MIT15_082JF10_lec01.pdf

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01 Project examples: Energy grid investments

01.02 PyPSA: Power System Analysis

Lets take a look at energy system modelling with PyPSA ...

- PyPSA minimizes the total system costs and can be used to simultaneously optimize dispatch and capacity of conversion technologies, stores and grid infrastructure.
- The package has predefined components, for example
 - Generators
 - Stores
 - Links
 - Loads
- Moreover, every component has predefined properties, for example all components that convert, transfer or store energy have **fixed** and **variable costs**.
- The loads are inelastic and have to be met for every time step.
- The dispatch and capacity variables are continuous. Therefore, the resulting optimization problem is linear, if unit commitment for generators is not included.
- It's possible to model technologies, which can transfer energy in both directions (bidirectional edge).



01 Figure based on: T. Brown et al, Synergies of sector coupling and transmission extension in a cost-optimised, highly renewable European energy system, Energy, Vol. 160, Pages 720-739, 2018.

Optimization in practice © 2024 d-fine 01.02 PyPSA: Power System Analysis

Energy system modelling – Objective function



In PyPSA⁰¹ the objective function minimizes the sum of all capital and operational costs (variable part) for all components for the given time horizon.

$$\text{minimize } \sum_{n,s} c_{n,s} \overline{g}_{n,s} + \sum_{n,s} c_{n,s} \overline{h}_{n,s} + \sum_{l} c_{l} F_{l} + \sum_{t} w_{t} \left[\sum_{n,s} o_{n,s,t} g_{n,s,t} + \sum_{n,s} o_{n,s,t} h_{n,s,t} + \sum_{l,s} o_{l,t} f_{l,t} \right]$$

Variables/Parameters

$n \in N$	set of nodes/buses	$h_{n,s,t}$	energy from store s at bus n at time step t
$t \in T$	time step, which is called snapshot	$\overline{h}_{n,s}$	nominal energy of store s at bus n
$l \in L$	label of a branch	$f_{l,t}$	flow over branch l at time step t
$s \in S$	label for different technology types at each bus	F _l	capacity for branch <i>l</i>
$\overline{g}_{n,s}$	nominal power of technology s at bus n	<i>C</i> _{<i>n</i>,<i>s</i>}	costs for extending the nominal power of technology s at bus n by one MW
$g_{n,s,t}$	dispatch from technology s at bus n at time step t	0 _{<i>n</i>,<i>s</i>}	variable costs for technology s at bus n for each MWh of dispatch
w _t	weighting of time step t		

01 https://pypsa.readthedocs.io/en/latest/optimal_power_flow.html#objective-function

Energy system modelling – Other constraints



Most use-cases require **additional constraints** in order to represent **political goals** or **technology restrictions**. One example is the **reduction of CO₂-emissions**.⁰¹ Keep in mind this actual constraint depends highly on the specific model and how CO₂ emissions are included.

$$\sum_{n,s,t} \frac{1}{\eta_{n,s}} w_t * g_{n,s,t} * e_{n,s} + \sum_{n,s} (e_{n,s,t=-1} - e_{n,s,t=|T|-1}) * e_{n,s} \le CAP_{CO2}$$

Variables/Parameters Example⁰² – PyPSA-Eur-Sec efficiency generator s at bus n $\eta_{n.s}$ generator $g_{m,w}$ with CO₂weighting of time step temissions W_t $e_{m,w}$ dispatch from technology s at bus n at time step tg_{n.s.t} bus m CO_2 -equivalent-tonne-per-MWh of the energy carrier of generator/store s at $e_{n.s}$ bus n energy in store s at bus n at time step t $e_{n,s,t}$ load d_m CAP_{co2} upper limit on CO₂-equivalent emissions in t/MWh store $h_{m,s}$ **Note:** The shadow price of this equation is the system wide CO_2 price. CO₂-Emissions

01 https://pypsa.readthedocs.io/en/latest/optimal_power_flow.html#global-constraints 02 https://github.com/PyPSA/pypsa-eur-sec

PROJECT EXAMPLE: ENERGY GRID INVESTMENTS

01.03 Outlook

Renewable energies are gaining ground and energy costs are rising



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The grids are a connecting element and enable the energy transition

ENERGY GRIDS AS FACILITATORS OF THE ENERGY TRANSITION

The transportation and distribution of individual energy sources will change significantly as a result of sectoral integration:

Few, centralized producers \rightarrow many, decentralized consumers \rightarrow prosumers

 $\text{Gas imports} \rightarrow \text{Biogas \& syngas}$

 $CH4 \rightarrow H2$ admixture, hydrogen network

THE POSSIBLE ADDITIONAL ROLE OF NETWORK OPERATORS

The new challenges are turning grid operators into service providers and points of contact for customer-specific questions:

- Should I produce my own hydrogen or obtain it from the grid?
- How can I operate my vehicle fleet in a grid-friendly way?
- Are there potential customers for my waste heat?
- How can I make optimum use of the energy generated on site?





OPTIMIZATION IN PRACTICE

02 Project example: Optimization of Remedial Actions

PROJECT EXAMPLE: OPTIMIZATION OF REMEDIAL ACTIONS

02.01 Project Background

Motivation and background

The European energy grid is subject to fluctuations and uncertainties

- The share of renewable energies in the grid is steadily increasing
- Renewable energies are subject to strong fluctuations and uncertainties
- The energy grid must be increasingly protected against unexpected fluctuations





Energy production and consumption must be balanced



The grid must be able to transport energy from the producer to the consumer



The grid must remain stable even in the event of outages

01 https://www.entsoe.eu/data/map/



Grid stability must remain guaranteed even with increasing uncertainties.

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Remedial actions (RAs) are used to maintain **grid stability**. Various remedial actions are available to eliminate congestion on grid elements. Some are triggered automatically, others can be controlled by the operator.



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2 Project example: Optimization 02.01 Project of Remedial Actions



of Remedial Actions

Remedial actions (RAs) are used to maintain **grid stability**. Various remedial actions are available to eliminate congestion on grid elements. Some are triggered automatically, others can be controlled by the operator.



Remedial actions (RAs) are used to maintain grid stability. Various remedial actions are available to eliminate congestion on grid elements. Some are triggered automatically, others can be controlled by the operator. Redispatch
Network element
Network e



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02 Project example: Optimization 02.01 Pro of Remedial Actions PROJECT EXAMPLE: OPTIMIZATION OF REMEDIAL ACTIONS

02.02 Optimization Problem Formulation

Optimization problem for the application of remedial actions



The aim is to **reduce the cost** of using RAs. In addition, we can reduce the volume and number of RAs. In order to ensure grid stability, the **load flow limits** on the transmission lines must be adhered to.

$$\min_{RA} \sum c_{RA} B_{RA,ON} + c_{\Delta,RA} \sum \Delta P_{RA} + w_{n,RA} \sum |B_{RA}|$$

Variables / Parameters

B _{RA,ON}	Indicator for start/shutdown of RA
C _{RA}	Costs for start/shutdown of RA
$\Delta \boldsymbol{P}_{\boldsymbol{R}\boldsymbol{A}}$	Volume of redispatch of RA
$\boldsymbol{c}_{\Delta,\boldsymbol{R}\boldsymbol{A}}$	Costs per volume of redispatch of RA
B _{RA}	Indicator for use of RA
W _{n,RA}	Penalty for use of RA
$t\in 0,,T$	Time step
P ^t	Initial load flow at time t
P _{temp,max}	Temporary load flow limit
P _{perm,max}	Permanent load flow limit

Load flows must remain below the limit of the network elements.

• A temporary limit must never be exceeded in order to prevent network element failures.

$$P^t + \Delta P_{RA}^t \le P_{temp,max}$$

• A permanent limit allows small overloads for a short time. $P^t > P_{perm,max} \Rightarrow P^{t+k} + \Delta P_{RA}^{t+k} \le P_{perm,max}$

Grid balance

After the application of RA, the grid must be balanced, i.e. the sum of all power flow changes must be zero.

$$\sum \Delta P_{RA,up} + \sum \Delta P_{RA,down} = 0$$

Alternating current (AC) power-flow model



To ensure the security of the grid a **high accuracy** of the model is needed. We use an AC load flow model instead of an DC approximation. The AC power flow is a **non-linear** system of equations.

Active and reactive power balance

$$0 = -P_i + \sum_{\substack{k=1 \ n}}^n |V_i| |V_k| (G_{ik} \cos \theta_{ik} + B_{ik} \sin \theta_{ik})$$

$$0 = -Q_i + \sum_{\substack{k=1 \ k=1}}^n |V_i| |V_k| (G_{ik} \sin \theta_{ik} - B_{ik} \cos \theta_{ik})$$

Variables / Parameters

- **P**_i Active power at bus i
- **Q**_i Reactive power at bus i
- *V_i* Voltage magnitude at bus *i*
- $\boldsymbol{\theta}_{ik}$ Voltage angle between bus *i* and bus *k*
- G_{ik} real part of the bus admittance matrix of bus i and bus k
- **B**_{ik} reactive part of the bus admittance matrix of bus *i* and bus *k*

Newton-Raphson solution method

 $\begin{bmatrix} \Delta \theta \\ \Delta |V| \end{bmatrix} = -J^{-1} \begin{bmatrix} \Delta P \\ \Delta Q \end{bmatrix}$

with

$$\Delta P_{i} = -P_{i} + \sum_{\substack{k=1 \ n}}^{n} |V_{i}|| V_{k}| (G_{ik} \cos \theta_{ik} + B_{ik} \sin \theta_{ik})$$

$$\Delta Q_{i} = -Q_{i} + \sum_{\substack{k=1 \ n}}^{n} |V_{i}|| V_{k}| (G_{ik} \sin \theta_{ik} - B_{ik} \cos \theta_{ik})$$

$$J = \begin{bmatrix} \frac{\partial \Delta P}{\partial \theta} & \frac{\partial \Delta P}{\partial |V|} \\ \frac{\partial \Delta Q}{\partial \theta} & \frac{\partial \Delta Q}{\partial |V|} \end{bmatrix}$$

Open source remedial action optimization and capacity calculation



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Reach out to us with your questions!





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