CO@Work 2020 Gas Networks Introduction



September 2020

Online

http://co-at-work.zib.de

Topics are:

- 1. European Regulations
- 2. Gas Network Basics
- 3. Network Design
- 4. Gas Network Capacity
- 5. Gas Network Control

The Energy Team (ZIB, TU Berlin, MODAL GasLab)





... and me

50 bar 20 bar pipeline

$$\frac{\partial \rho}{\partial t} + \frac{\partial (\rho \, v)}{\partial x} = 0$$

$$\frac{\partial (\rho \, v)}{\partial t} + \frac{\partial (p + \rho \, v^2)}{\partial x} + \frac{\lambda}{2D} |v| \, v \, \rho + g \, s \, \rho = 0$$

$$\frac{\partial}{\partial t} \left(\rho (\frac{1}{2} v^2 + e) \right) + \frac{\partial}{\partial x} \left(\rho \, v (\frac{1}{2} v^2 + e) + p \, v \right) + \frac{k_w}{D} (T - T_w) = 0$$

 α depending on dimension and inclination of the pipeline, the friction in the pipeline, gas temperature, gas composition, outside temperature, and more.

 $\alpha |q|q = p_{out}^2 - p_{in}^2$

Given a graph G=(V,A) with pressure p_u , and flow q_a , for $u \in V$, $a \in A$ and $\pi_u = p_u^2$.

Exists q, π

subject to

$$\sum_{a \in \delta^{+}(u)} q_{a} - \sum_{a \in \delta^{-}(u)} q_{a} = d_{u} \quad \text{for all } u \in V$$

$$\alpha_{a} \mid q_{a} \mid q_{a} = \pi_{u} - \beta_{a} \pi_{v} \quad \text{for all } a = (u, v) \in A$$

$$\underline{\pi}_{u} \leq \pi_{u} \leq \overline{\pi}_{u} \quad \text{for all } u \in V$$

$$\underline{q}_{a} \leq q_{a} \leq \overline{q}_{a} \quad \text{for all } a \in A$$

$$d_{u} \qquad \text{for all } u \in V$$

$$\pi_{u} - \beta_{a}\pi_{v} \quad \text{for all } a = (u, v) \in A$$

Theorem (Maugis, 1977, Collins at al, 1978, Humpola, K., et al, 2013)

Let $d \in \mathbb{R}^V$ be a balanced demand and Φ_a strictly increasing function.

Then the solution space of

exists
$$q, \pi$$
 subject to
$$\sum_{a \in \delta^+(u)} q_a - \sum_{a \in \delta^-(u)} q_a = d_u \qquad \text{for all } u \in V$$

$$\Phi_a(q_a) = \pi_u - \pi_v \qquad \text{for all } a = (u, v) \in A$$

$$\underline{\pi}_u \leq \pi_u \leq \overline{\pi}_u \qquad \text{for all } u \in V$$

$$\underline{q}_a \leq q_a \leq \overline{q}_a \qquad \text{for all } a \in A$$

is either empty or fulfills the conditions:

- The flow is unique
- The squared pressure component π has the form

 $\{\pi^* + \eta^1 \mid \eta \le \eta \le \bar{\eta} \}$ for some π^* , η , $\bar{\eta}$.

- \triangleright Flow is unique and Φ_a is strictly increasing.
- $\triangleright \pi_{u} \pi_{v}$ are uniquely determined for all arcs.
- > Shifting all values by a constant is feasible.
- Constant shift is the only possible source of difference.
- Consider two feasible squared pressure vectors: π' und π'' .

Both are shifted in such a way that they coincide in the value

at u. The difference is constant which implies

$$\pi'_u - \pi'_v = \phi_a(q_a) = \pi''_u - \pi''_v.$$

Since $\pi'_{n} = \pi''_{n}$, we also have $\pi'_{n} = \pi''_{n}$.

The solution space of the problem

$$\min \sum_{u \in V} \Delta_u + \sum_{a \in A} \Delta_a$$

subject to

$$\sum_{a \in \delta^{+}(u)} q_{a} - \sum_{a \in \delta^{-}(u)} q_{a} = d_{u} \qquad \text{for all } u \in V$$

$$\Phi_{a}(q_{a}) = \pi_{u} - \pi_{v} \qquad \text{for all } a = (u, v)$$

$$\underline{\pi}_{u} - \Delta_{u} \leq \overline{\pi}_{u} \qquad \text{for all } u \in V$$

$$\underline{\pi}_{u} + \Delta_{u} \geq \underline{\pi}_{u} \qquad \text{for all } u \in V$$

$$\Delta_{u} \geq 0 \qquad \text{for all } u \in V$$

$$q_{a} - \Delta_{a} \leq \overline{q}_{a} \qquad \text{for all } a \in A$$

$$q_{a} + \Delta_{a} \geq \underline{q}_{a} \qquad \text{for all } a \in A$$

$$\Delta_{a} \geq 0 \qquad \text{for all } a \in A$$

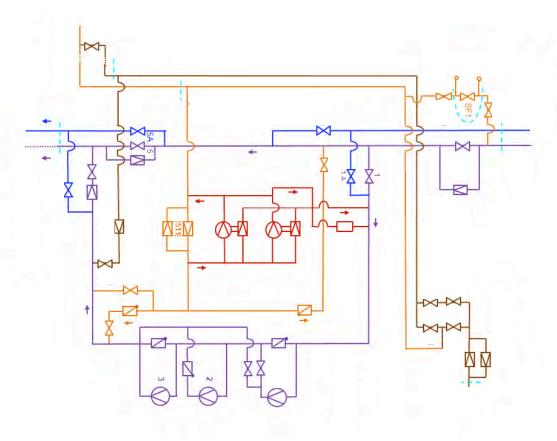
is non-empty and is convex.

Active elements in gas networks

Element	Function	Symbol	
Valve	Switch on/off		
Regulator	Decrease _ pressure		
Compressor	Increase pressure		

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This is an example of just a compressor station

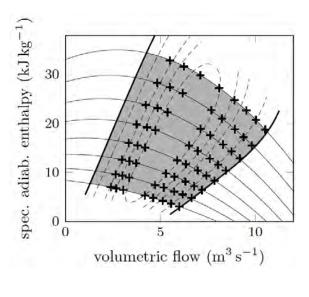


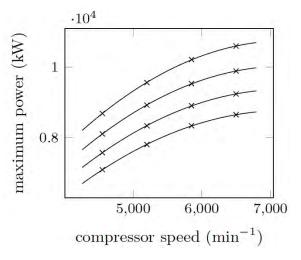
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Compressor machines

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Compressor performance depends on input pressure, output pressure, flow, temperature, composition, compressor power.





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Compressor stations

re-in

How precise can we model a compressor?

Let us assume we assume the gas temperature 10°C too low.

This gives about 3% more power to the compressor station.

This might be enough to get another 1500 MW gas through.

 M_1

 M_2



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bypass

 M_2

Design a new network (or extend an existing one)

Determine the capacity of a given network

Control a network to achieve maximum efficiency



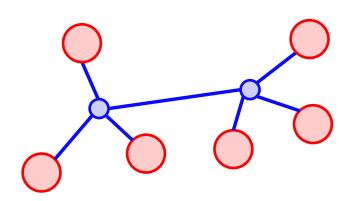
Network Design

(Just a teaser)

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The Steiner tree problem in graphs (STP)

Given an undirected connected graph G = (V, E), costs $c: E \to \mathbb{Q}^+$ and a set $T \subset V$ of *terminals*, find a minimum weight tree $S \subset G$ which spans T.

The STP is one of the classical 21 **NP**-hard problems.

Direct Cut Integer Programming Formulation for SAP



min aTax		
$min c^T y$		

subject to
$$y(\delta_W^+) \ge 1, \qquad \text{for all } W \subset V, r \in W, (V \setminus W) \cap T \ne \emptyset$$

$$(= 0, \text{if } v = r;$$

$$y(\delta_{v}^{-}) \begin{cases} = 0, & \text{if } v = r; \\ = 1, & \text{if } v \in T \setminus r; & \text{for all } v \in V \\ \leq 1, & \text{if } v \in N \end{cases}$$

$$y(\delta_{v}^{-}) \le y(\delta_{v}^{+}), \quad \text{for all } v \in N;$$

for all
$$v \in N$$
;

for all
$$a \in \delta_v^+, v \in N$$
;

for all
$$a \in A$$
;

$$y_a \in \{0,1\},$$
 for all $a \in A$,

Cores, CPAIOR 2019, LNCS 11494, and the references there in.

 $y\left(\delta_{v}^{-}\right) \geq y_{a}$

 $0 \le y_a \le 1$,

$$N = V \setminus T$$
, $\delta_X^+ := \{(u, v) \in A | u \in X, v \in V \setminus X\}$, $\delta_X^- := \delta_{V \setminus X}^+$ for $X \subset V$.

See, e.g., Koch, Martin, Solving Steiner tree problems in graphs to optimality, Networks (1998) Polzin, Algorithms for the Steiner problem in networks, Uni Saarland, 2004, Rehfeldt, Koch, Combining NP-Hard Reduction Techniques and Strong Heuristics in an Exact Algorithm for the Maximum-Weight Connected Subgraph Problem, SIAMOPT (2019), Shinano, Rehfeldt, Koch, Building Optimal Steiner Trees on Supercomputers by Using up to 43,000

It is part of the SCIP Optimization Suite and can solve:

- Steiner Tree Problem in Graphs (STP)

- Node-weighted Steiner Tree (NWSTP)
- Prize-collecting Steiner Tree (PCSTP)
- Rooted Prize-collecting Steiner Tree (RPCSTP)
- Maximum-weight Connected Subgraph (MWCSP)
- Degree-constrained Steiner Tree (DCSTP)
- ▶ Hop-constrained directed Steiner Tree (HCDSTP)

http://scipopt.org





Please continue with the lecture on Gas Network Cacapcity



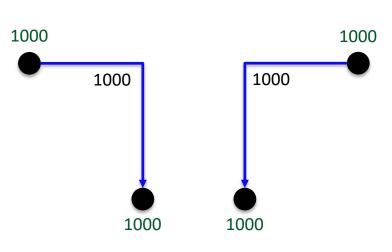


Gas Network Capacity

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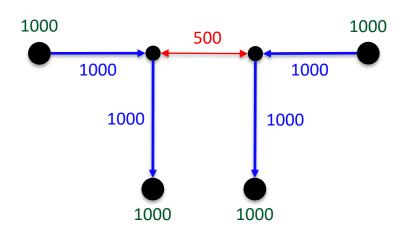
The *Technical Capacity* is defined as the maximum flow bounds at the entry- and exit-nodes, such that any possible balanced demand scenario within these bounds can be fulfilled by the network.





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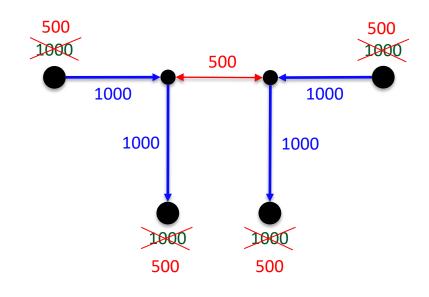
Now adding a connection...





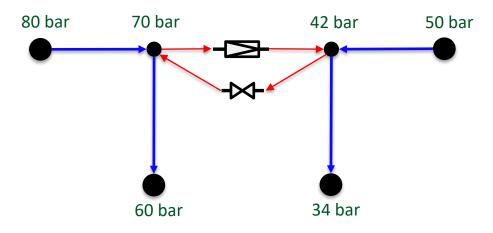
The *Technical Capacity* is defined as the maximum flow bounds at the entry- and exit-nodes, such that any possible balanced demand scenario within these bounds can be fulfilled by the network.

Now adding a connection ... does not necessarily increase it.



The new connection also adds restrictions due to pressure coupling. Not all splits of the inflow between the two entries are easily possible anymore.

See also Braess's paradox.



Advantages

- > This is quite realistic (depending on the time step size)
- Disadvantages
- Can only be computed over a finite time horizon
- ▶ Requires a forecast of the in- and outflow over time
- ▶ Requires a start state, which is not known for planning
- Deviations between the predicted and the physical network state grow over time
- If we want to decide the feasibility of a future demand scenario should we test against:
- ▷ A worst case start state? Far too pessimistic
- ▷ All possible start states? Infinitely many
- ➤ A suitable start state? Likely overly optimistic

Stationary models describe a (timeless) equilibrium network state.

Advantages

- > Stable situation (by definition) modelling an "average network" state
- No start state needed, no time horizon to consider
- ▶ Ensures that the situation is sustainable (we cannot paint ourselves easily into a corner)

Disadvantages

- □ Using pipes as gas storage (linepack) cannot be modelled
- > Transition between states cannot be modelled
- ▶ Too pessimistic, especially regarding short-term peak situations

Often better suited for medium and long-term planning.

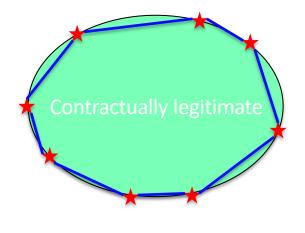
Given a directed graph G = (V, A) that models a gas network. The arcs represent the elements of the network. We distinguish between passive network elements (pipes and resistors), whose behavior cannot be influenced, and active network elements (valves, control valves, and compressors), which allow to control the network. The active and passive elements are collected in the arc sets A_{active} and $A_{passive}$, respectively.

Demand Scenario

d specifies for each $u \in V$ the amount of flow that enters $(d_u \ge 0)$ or leaves $(d_u \le 0)$ the network at u. The scenario d is balanced, i.e., we have

$$\sum_{u\in V}d_u=0.$$

The task is to decide, whether or not the scenario *d* can be realized in the network by controlling the active elements.



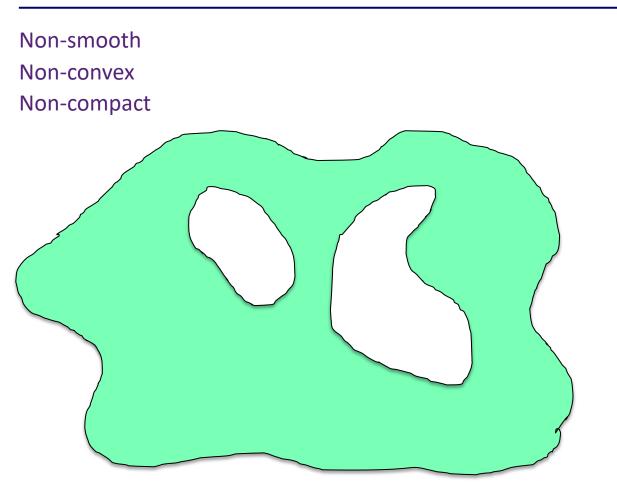
Contractually illegitimate

A possible approach:

- Experts derive scenarios that are on the border of feasibility.
- These scenarios are checked using stationary models.
- 3. If they are feasible, it is concluded that also all other scenarios are feasible.

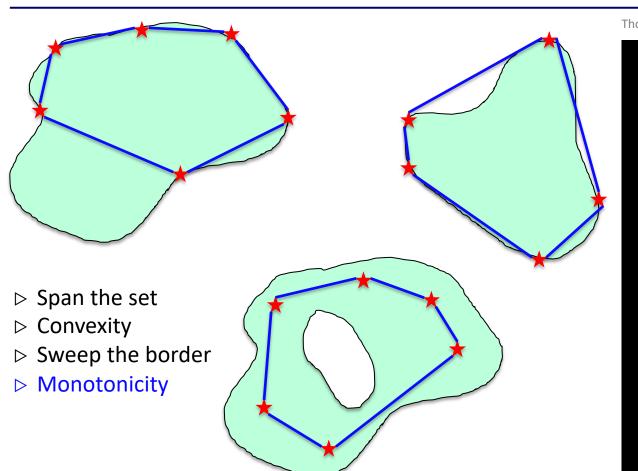
Assumptions on the Set of all feasible Scenarios





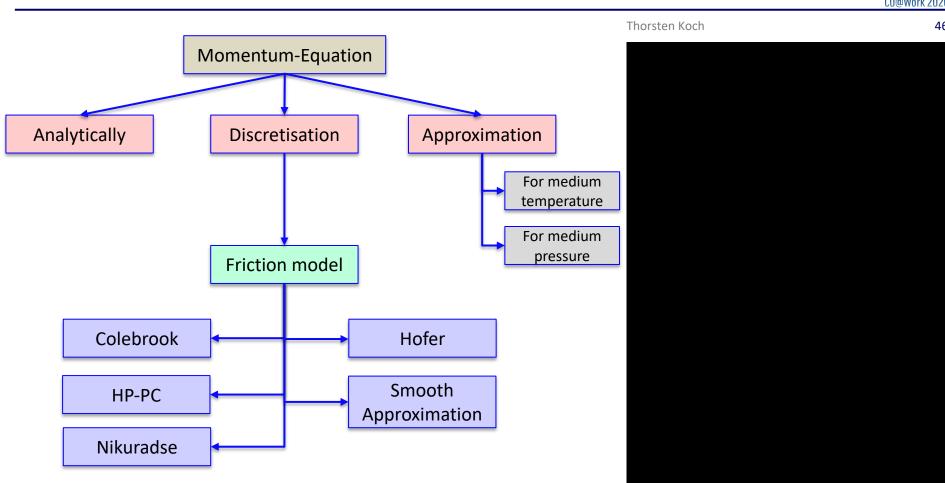
Assumptions on the Scenarios



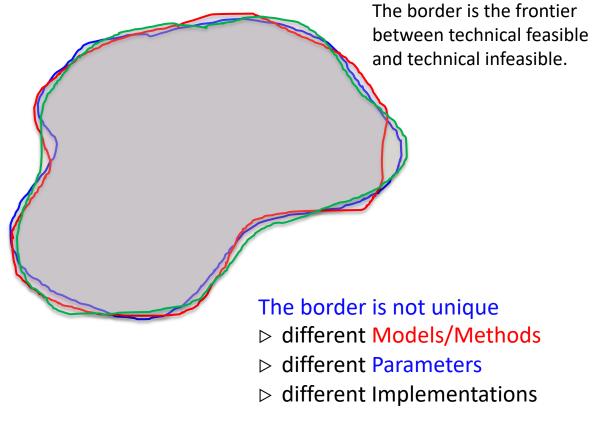


Decisions regarding the Momentum-Equation

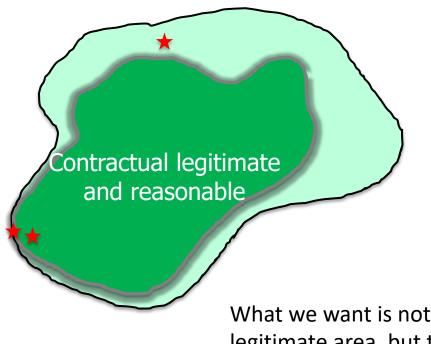




Assumptions on the Border



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What we want is not the contractual legitimate area, but the contractual legitimate and reasonable area.

This area is not well defined.



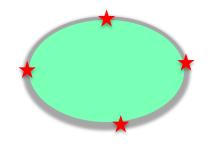


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We are able to generate scenarios and test their technical feasibility (with some limitations).

Generation of scenarios:

- Manual generation of expert scenarios
 - limited number,
 - + high quality
- Automatic generation of extreme value scenarios
 - difficult to distinguish between contractual legitimate and reasonable,
 - + high number
- Automatic generation of stochastic scenarios
 - seldom extreme,
 - + reasonable, + high number, + probable distribution







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Advantages:

- High Quality
- Very well understood

Problems:

▶ Risk of being too much tuned towards a particular model, parameter setting, or implementation "let us see how far we can drive this"

Disadvantages:

- ► Small number
- Complete coverage of the feasible set is hard to ensure
- Only extreme value scenarios, i.e., the probability for the scenarios to happen in reality is nearly zero

Advantages:

- High number
- Can be generated with different methods

Problems:

► Hard to detect *contractual legitimate but unreasonable*

Disadvantages:

- Only the border of the feasible set is covered
- Only extreme value scenarios, i.e. the probability for the scenarios to happen in reality is nearly zero

Advantages:

- High number
- Can be generated with different methods
- ► Realistic
- ► Coverage of the inner part of the feasible set
- Can be attributed with probabilities

Problems:

- ► Methods for generation are involved and need much data
- ► Refer to the past

Disadvantages:

 Extreme values occur seldom since they are not probable to happen C0@Work 2020

- If all three methods are combined, there are nearly no disadvantages left.
- This may lead to a huge number of scenarios of which many are possibly similar.
- ► This can be countered by methods for scenario reduction.
- ► Testing the technical feasibility of the scenarios has necessarily to happen automatically.
- ► This can be troublesome regarding extremal value scenarios.
- Now it is possible to automatically validate scenarios.
- ► This can be extended to compute capacities.
- It is possible to extend these concepts to answer more sophisticated questions, e.g. looking at probabilities for buy back happening when overbooking.

Simulation:

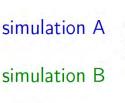
- allows very accurate gas physics models
- Relies on human experience to decide feasibility
- Therefore cannot determine infeasibility

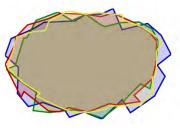
Optimization:

Works on simplified models of gas physics Thorsten Koch

- Automatically finds settings for active elements
- Eventually can prove infeasibility of a scenario

Beware: different solution spaces due to different modeling





optimization A

optimization B

Forschungskooperation Netzoptimierung





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Technische Universität Darmstadt

Discrete Optimization

Prof. Dr. Marc Pfetsch



Friedrich-Alexander Universität Erlangen-Nürnberg Economics - Discrete Optimization -





Universität Duisburg-Essen Department of Mathematics Prof. Dr. Rüdiger Schultz



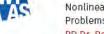
Leibniz-Universität Hannover Institute for Applied Mathematics Prof. Dr. Marc Steinbach



Humboldt-Universität zu Berlin Department of Mathematics Prof. Dr. Werner Römisch



Weierstraß-Institut für Angewandte Analysis und Stochastik (WIAS) Nonlinear Optimization and Inverse Problems



PD Dr. René Henrion



BMWi Projektträger Jülich Energy Business Area



develOPT GmbH Big Data Optimization Dr. Antonio Morsi, Dr. Björn Geißler





Open Grid Europe GmbH Netzplanung und -steuerung / Netzoptimierung Klaus Spreckelsen

atesio GmbH Dr. Andreas Eisenblätter. Dr. Benjamin Hiller

Goal of the project:

Build an automatic system that given a network and a set of supplies and demands at the border points computes settings for the active elements of the network such that the resulting stationary scenario is feasible.

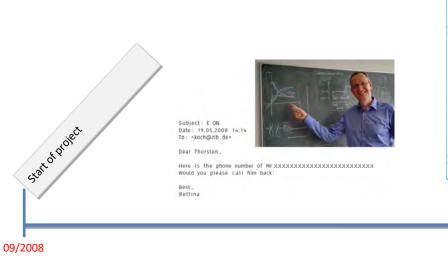






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Nova Progress



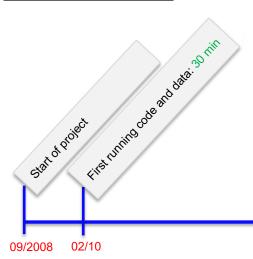


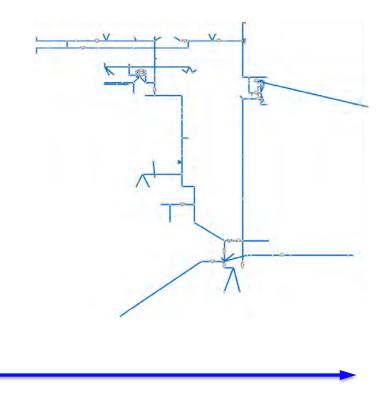
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Element	Count
Pipes	136
Compressor groups	3
Resistors	8
Control valves	7
Valves	1
Entries	26
Exits	14



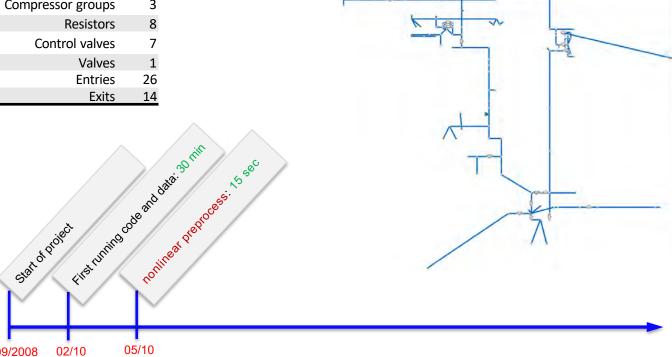




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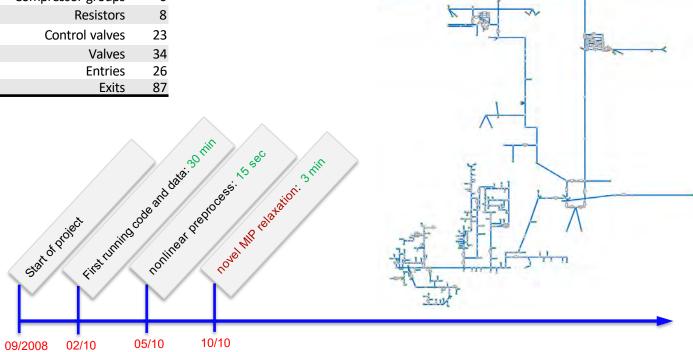
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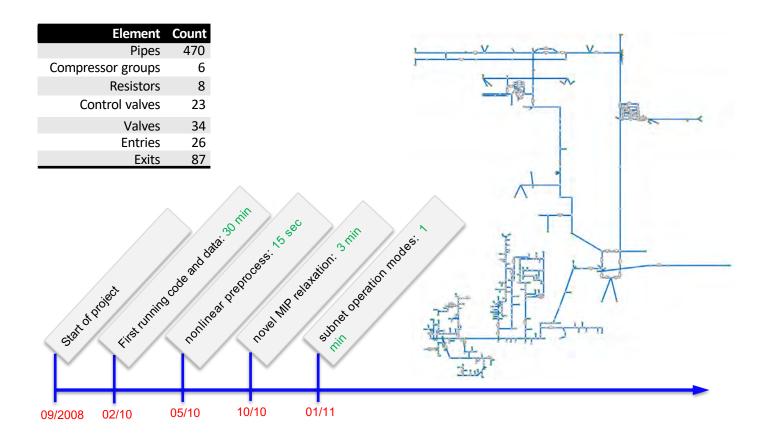


Element	Count
Pipes	470
Compressor groups	6
Resistors	8
Control valves	23
Valves	34
Entries	26
Exits	87
·	



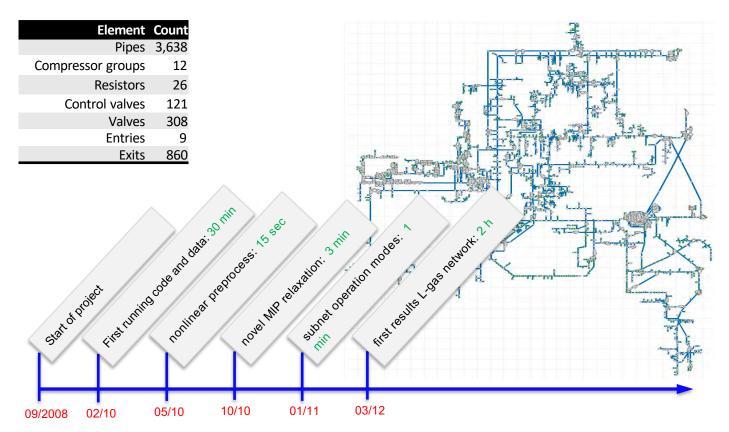






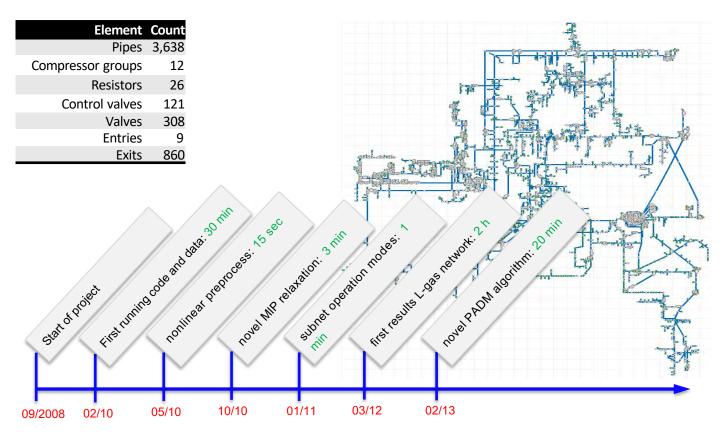














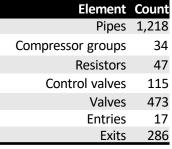
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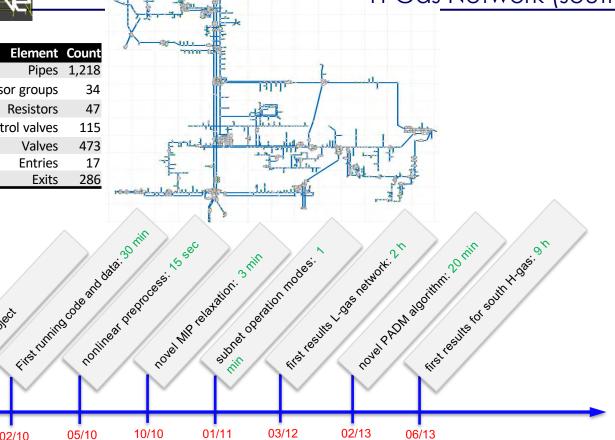
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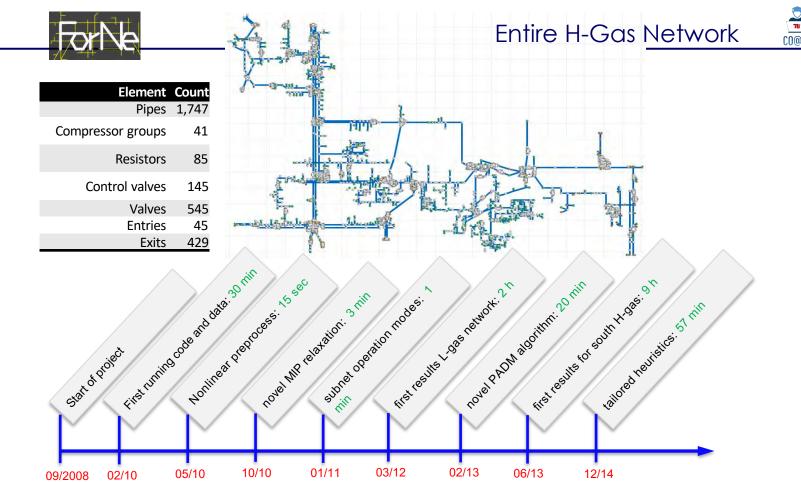
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H-Gas Network (south)











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The Research Cooperation Network Optimization ForNe ran for 6 years and involved

more than 30 people from around 10 universities and institutes along with more than 10 employees from Germany's largest gas network system operator OGE.

← Here are the results.

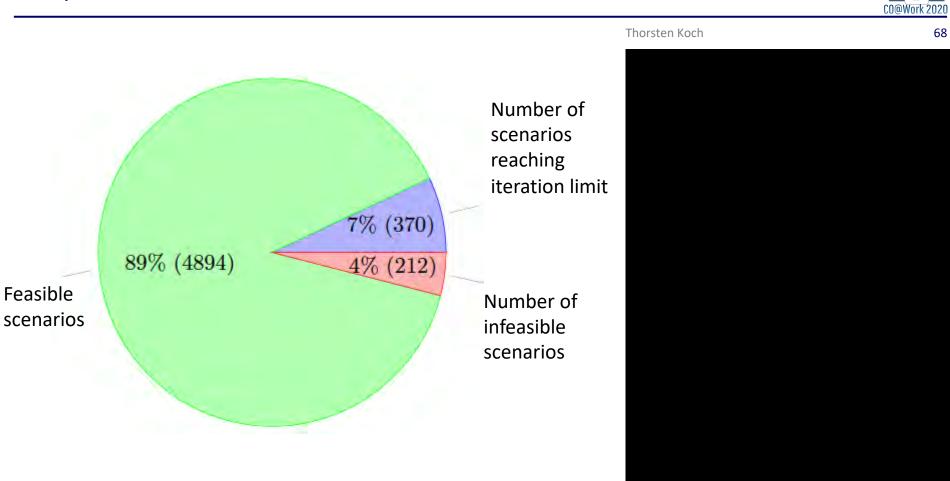
GAS NETWORK CAPACITIES





Computational outcome

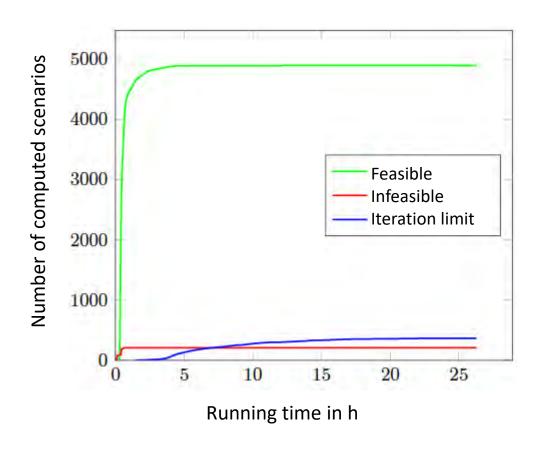




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(negotiation).

- Technology is changing all the time, new systems mix with existing ones
- Thorsten Koch
- ▶ Often hard to determine actual system limits
 - (many assumptions are necessary for optimization)
 - Optimization drives errors to cluster in one direction
- ► For larger models/scenarios hard to check against reality
 - Marketization makes it difficult to predict behavior of participants, since the objectives of the individual players are unknown, and the outcome is result of a game

(also very hard to find data errors/inconsistencies)

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Relevant real-world questions can be tackled efficiently with mathematical optimization and algorithmic intelligence.

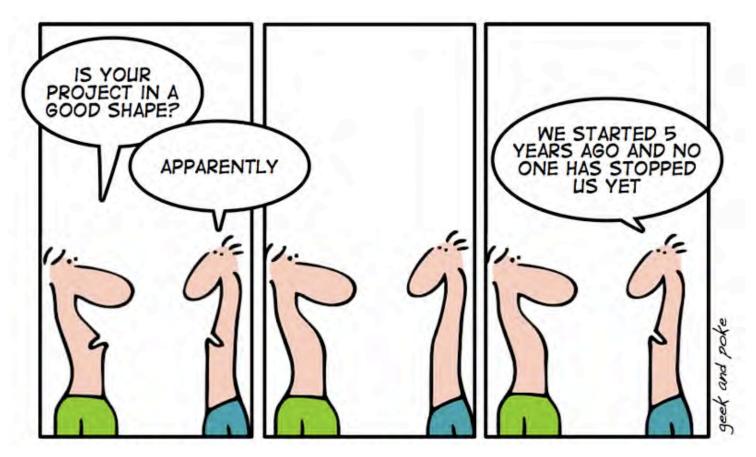
However,

- a substantial effort is needed to succeed,
- the setup cost is high compared to pure research,
- close cooperation with practitioners is indispensable,
- different disciplines need to collaborate,
- access to and curation of data is essential.

Good luck!

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Thank you very much





Please continue with the lecture on Gas Network Control

