

Planning and Optimizing Large Scale Telecommunication Networks

CO@Work

October 5, 2009

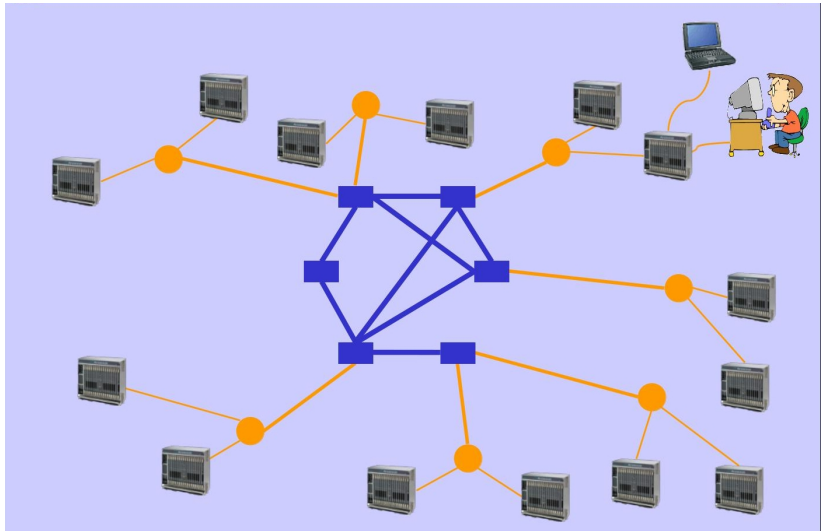


Maren Martens
Andreas Bley, Christian Raack

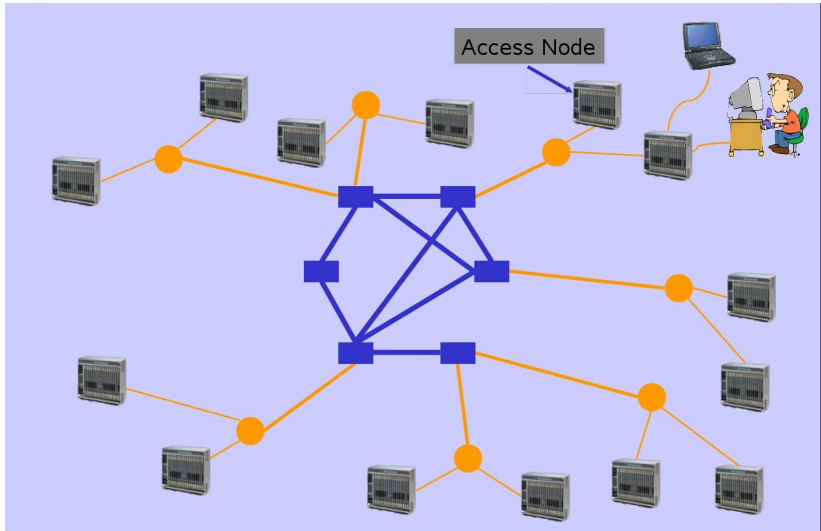
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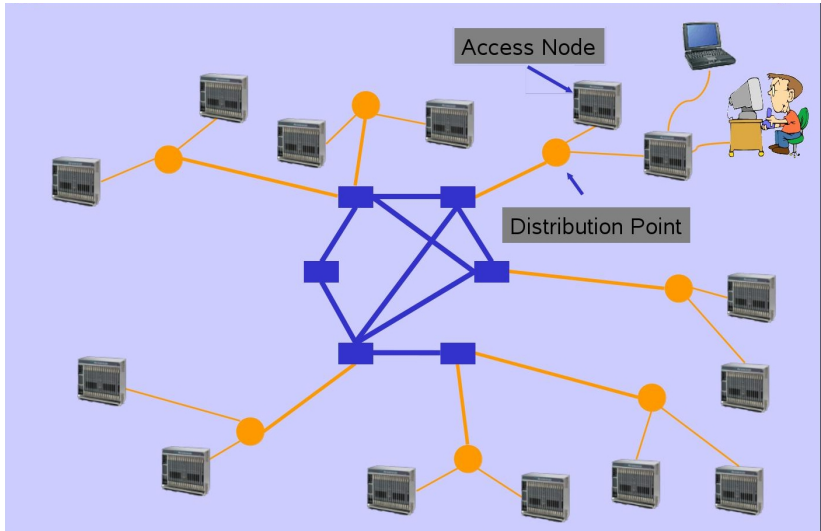
A Telecommunication Network



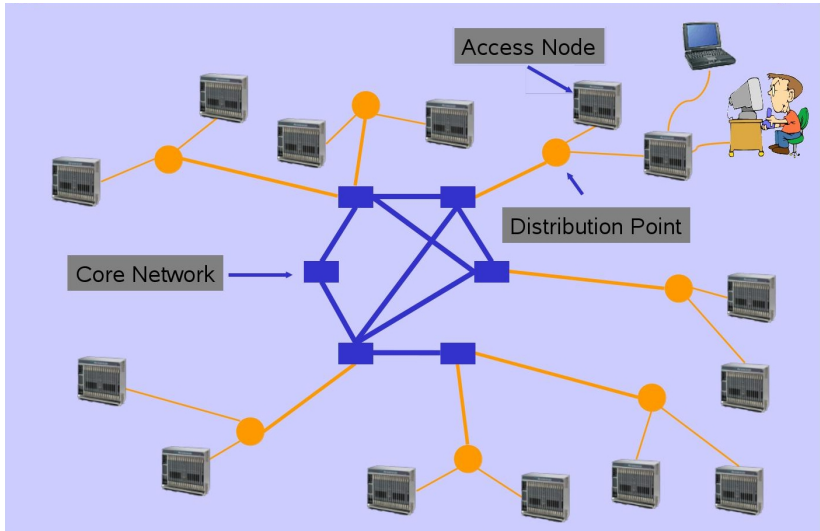
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A Telecommunication Network



Planning Problems

Access Networks:

- How to connect customers to given routers?

Core Networks:

- Which links to use between routers?

Survivability:

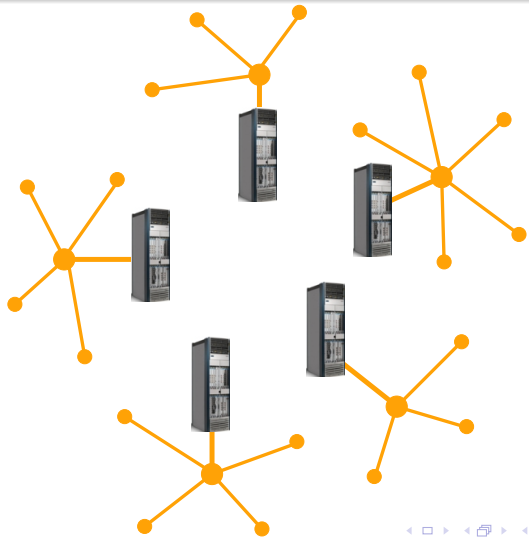
- How to avoid interruptions?

Demands:

- Given customer demands, how to route them?

ACCESS NETWORKS

Access Networks

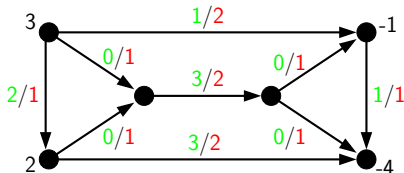


The Minimum Cost Flow Problem (MCFP)

Given: Digraph $D = (V, A)$, demands/supplies $b_v \in \mathbb{R}_0^+$ ($v \in V$)
with $\sum_{v \in V} b_v = 0$, arc cost c_a and capacities u_a ($a \in A$)

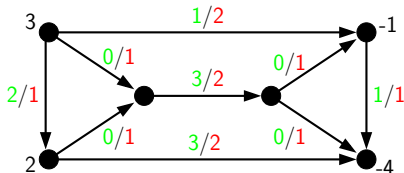
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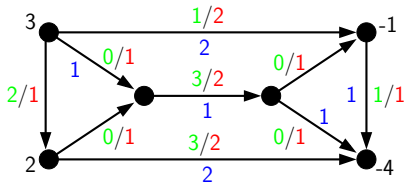
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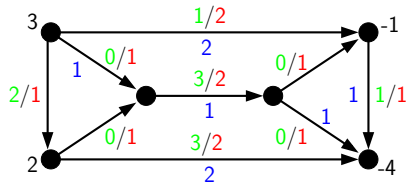
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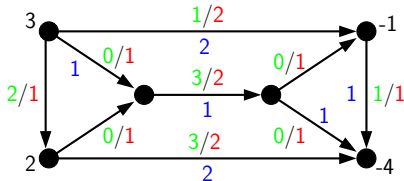


total cost = 13

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$$\min \sum_{a \in A} c_a f(a)$$

$$\text{s.t.} \quad \sum_{a \in \delta^+(v)} f(a) - \sum_{a \in \delta^-(v)} f(a) = b_v \quad \forall v \in V$$

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Access Networks and the MCFP

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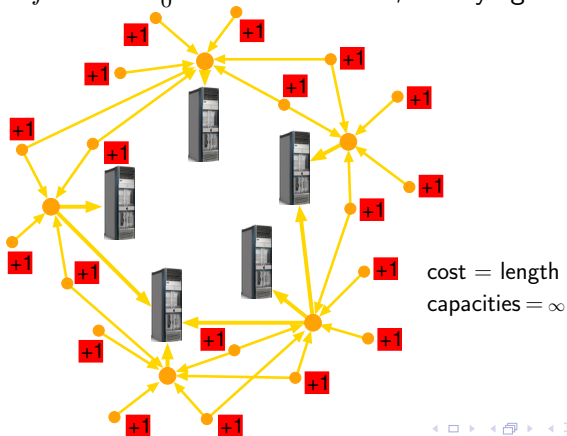
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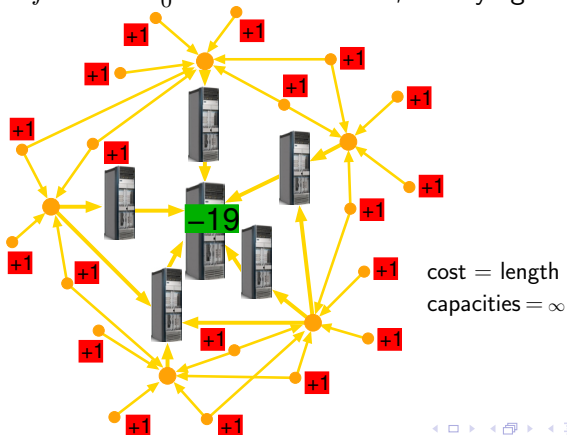
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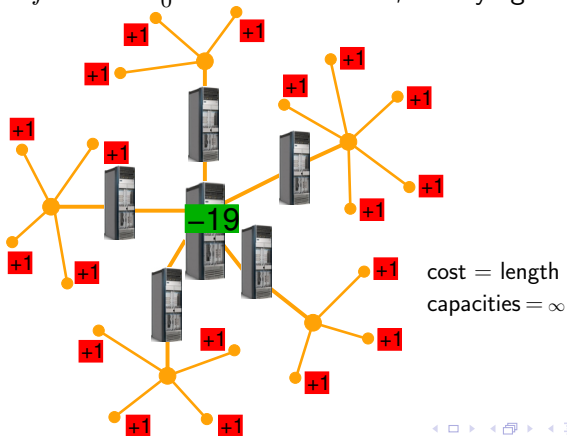
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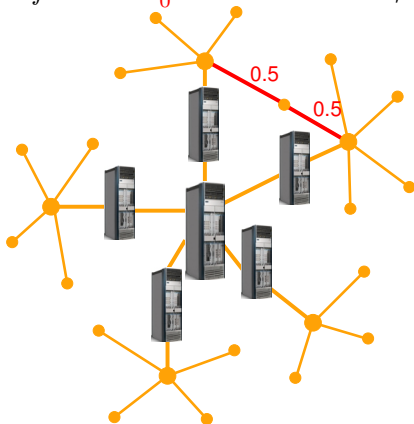
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$\rightarrow f_e$ integral!

Algorithms for MCFP

$$\begin{aligned}
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→ Solvable in polynomial time for $f(a) \in \mathbb{R}_0^+$!

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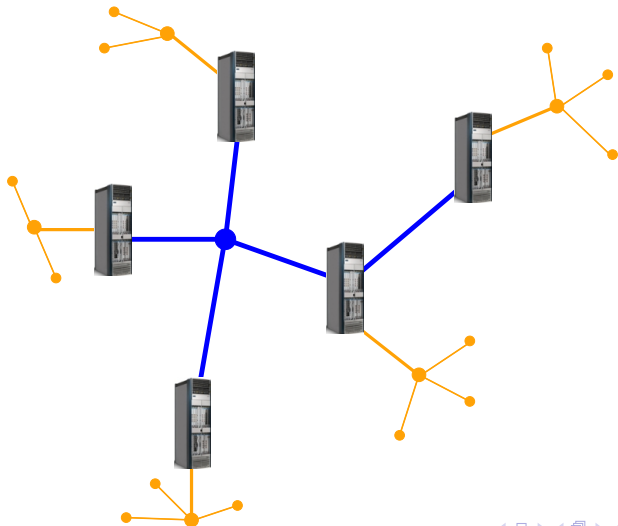
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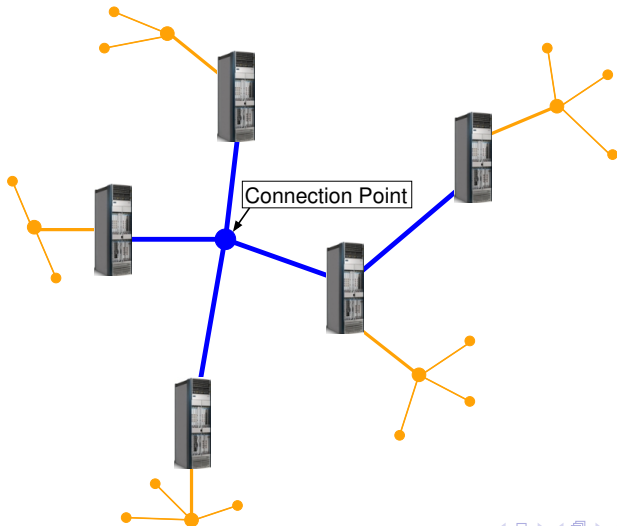
Both give integral optimal solution, if b and u are integral!

CORE NETWORKS

A Core Network



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Steiner Trees

Definition

Given a graph $G = (V, E)$ with *terminals* $T \subseteq V$, a *Steiner tree* is a tree $S \subseteq E$ that connects all terminals in T .

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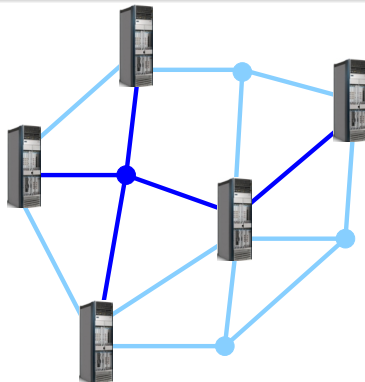
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The Steiner Tree Problem

Definition

Given: $G = (V, E)$, terminals $T \subseteq V$, edge weights c_e ($e \in E$)

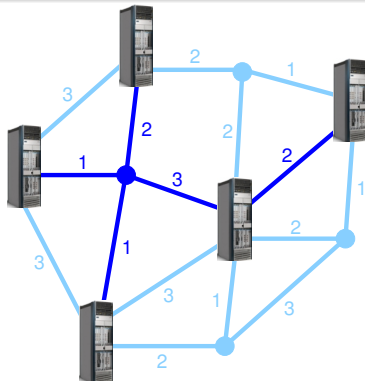
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Simple special cases:

- $|T| = 2$: Shortest Path Problem
- $T = V$: Minimum Spanning Tree Problem

Formulation via Cuts (undirected)

Aneja 1980:

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & x(\delta(U)) \geq 1 \quad \forall U \subset V : \emptyset \neq U \cap T \neq T \\ & x_e \in \mathbb{Z}_0^+ \quad \forall e \in E \end{aligned}$$

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- The LP relaxation can also be solved in polynomial time.
(separation time \approx optimization time, [GLS1988])

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Directed vs. Undirected

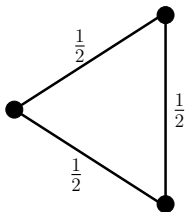
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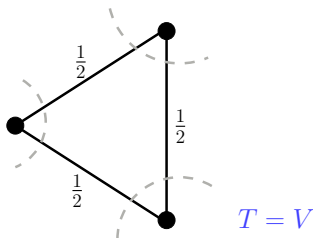
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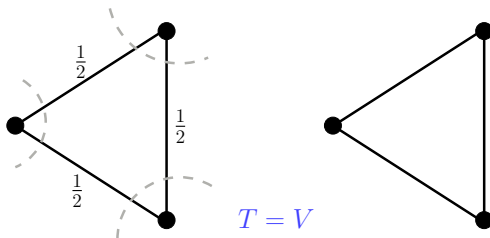
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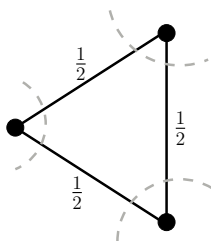
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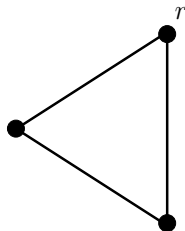


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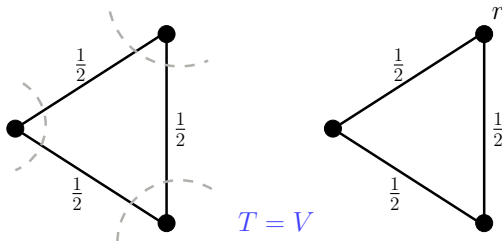


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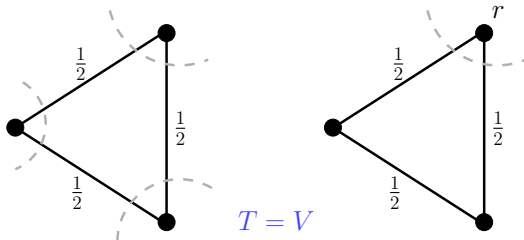
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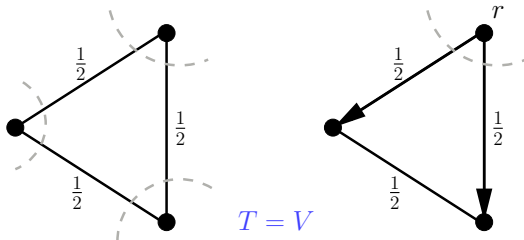
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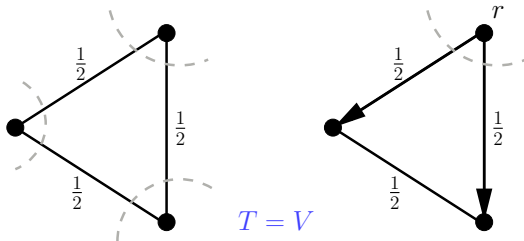
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Theorem

The directed cut formulation is stronger than the undirected cut formulation.

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Problem with cuts: There are too many!

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On digraph $D = (V, A)$ with root $r \in T$ and $T' := T \setminus \{r\}$:

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$$x_e \in \mathbb{Z}_0^+ \quad \forall e \in E$$

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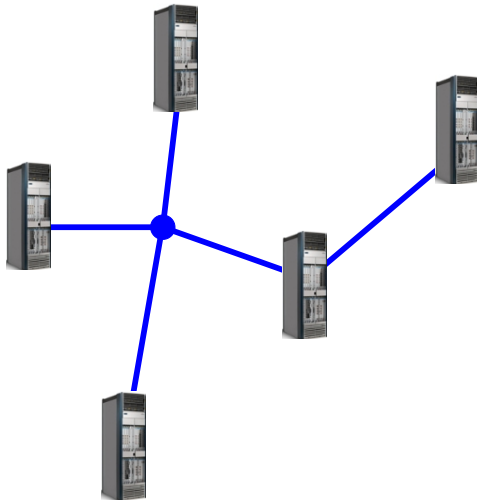
$$f_s(i, j) + f_t(j, i) \leq x_{\{i, j\}} \quad \forall s, t \in T', \{i, j\} \in E$$

$$f_t(a) \geq 0 \quad \forall t \in T', a \in A$$

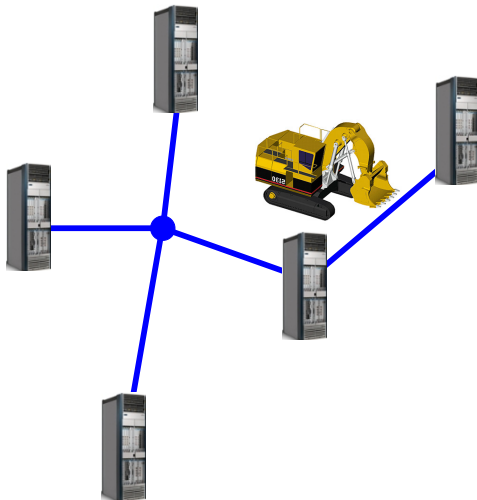
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SURVIVABILITY

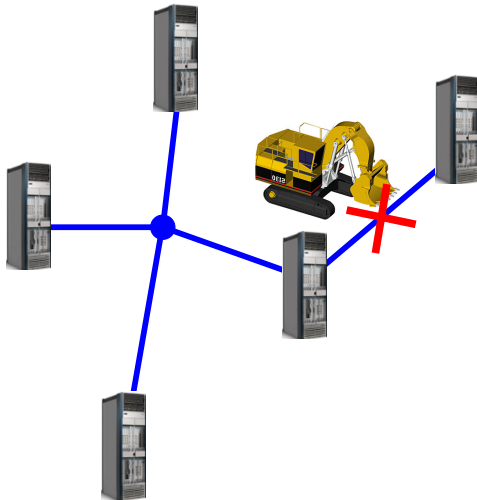
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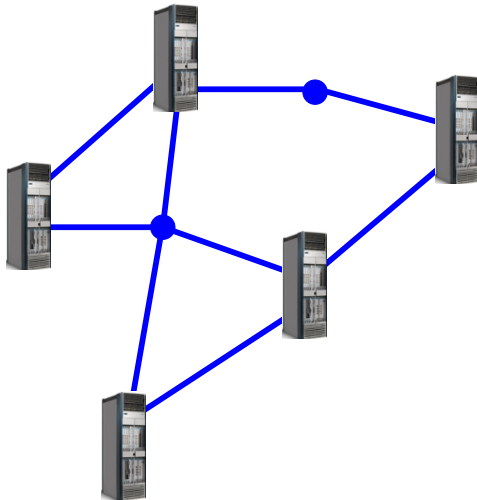
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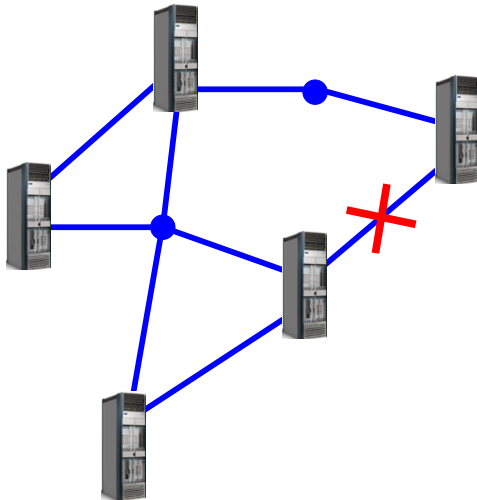
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Given: $G = (V, E)$, edge cost c_e ($e \in E$)

Find: Minimum cost subgraph containing all $v \in V$ and having 2 node/edge-disjoint s - t -paths for all $s, t \in V$

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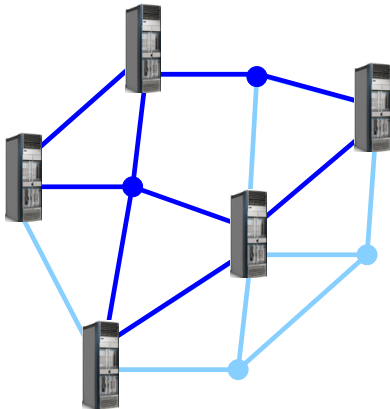
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{0,1,2}-Survivable Network Design ({0,1,2}-SND)

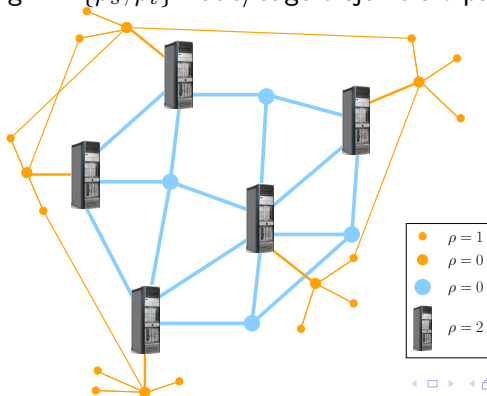
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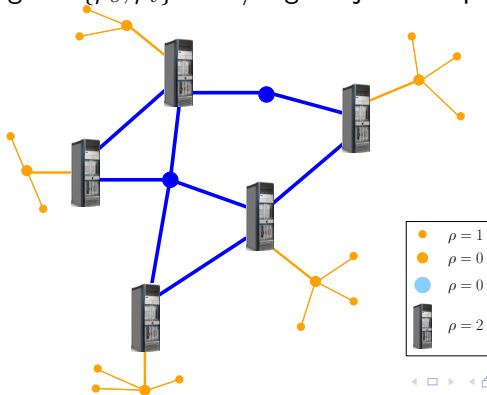
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Algorithms for {0,1,2}-SND

Theorem

{0,1,2}-SND is NP-hard.

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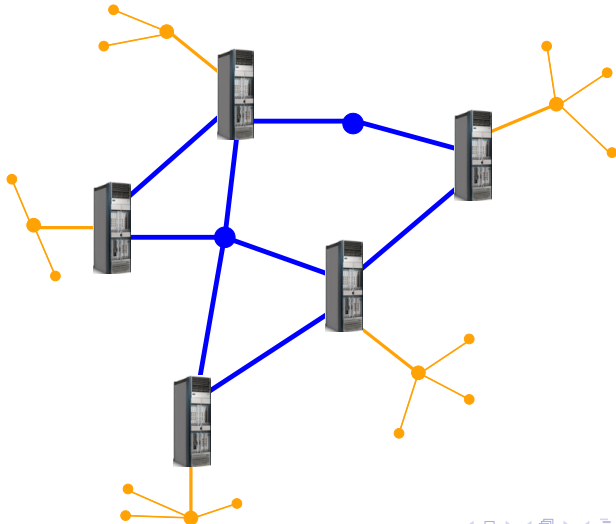
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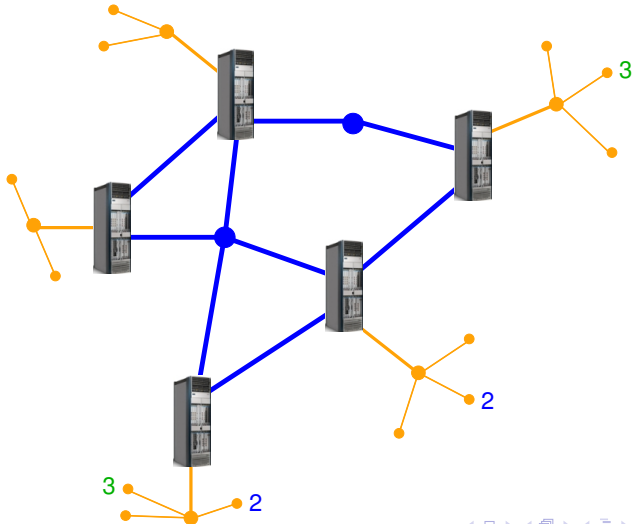
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DEMANDS AND CAPACITIES

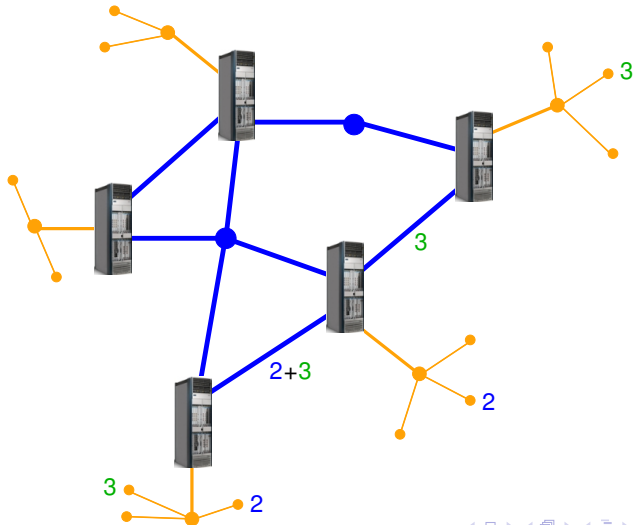
Are we done yet?



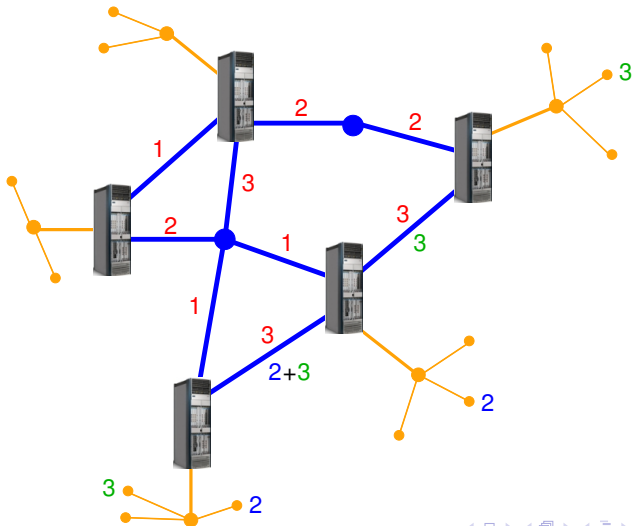
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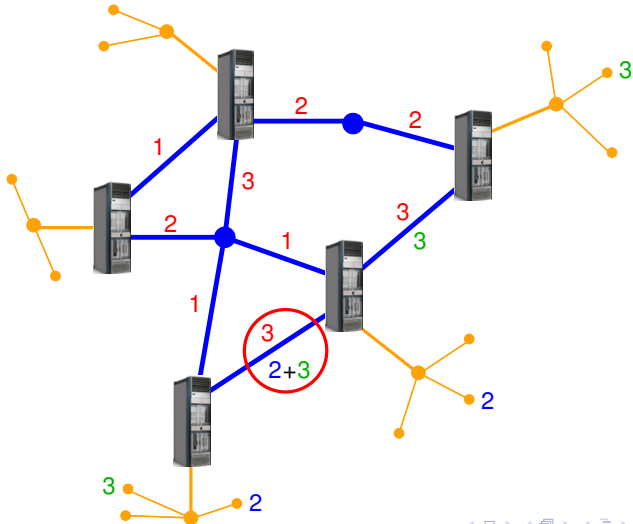
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Connectivity and Flows

Given: $G = (V, E)$, commodities $(s, t) \in V \times V$ with demands d_{st} ,
capacity modules $k \in K$ with capacities u_k , cost c_k

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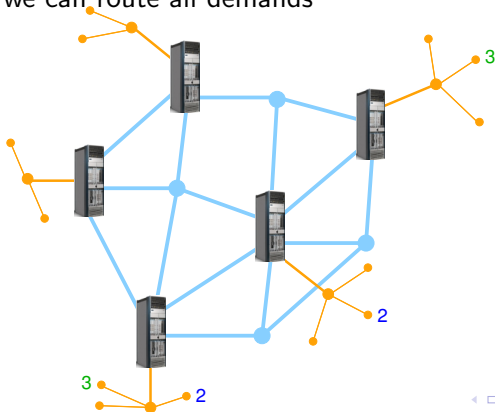
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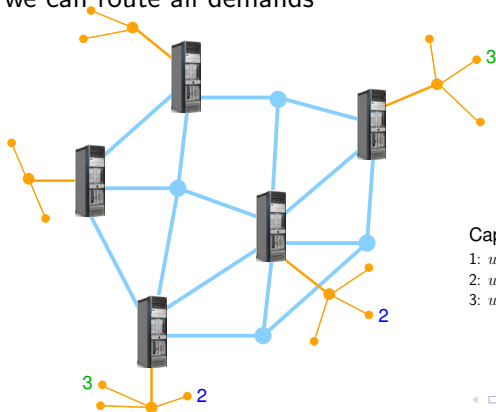
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Capacity modules:

1: $u_1 = 2$, $c_1 = 20$

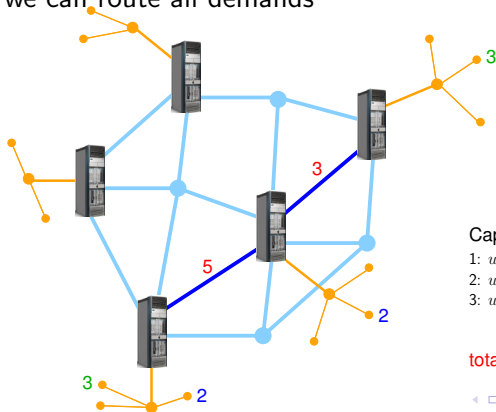
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total cost for core: 55

IP Formulation (Connectivity and Flows)

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[for $e = \{i, j\} \in E$: directed arcs $a_e = (i, j)$ and $\overleftarrow{a_e} = (j, i)$]

How to realize survivability?

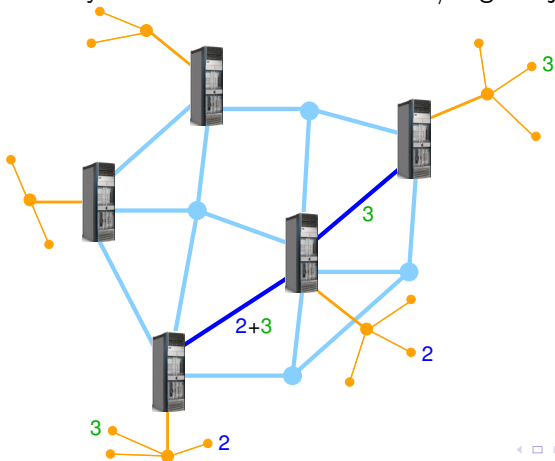
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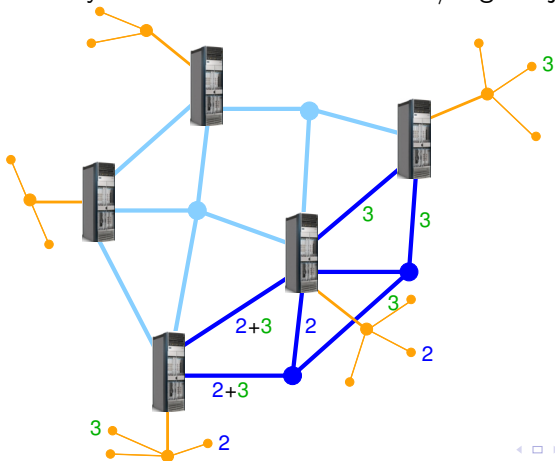
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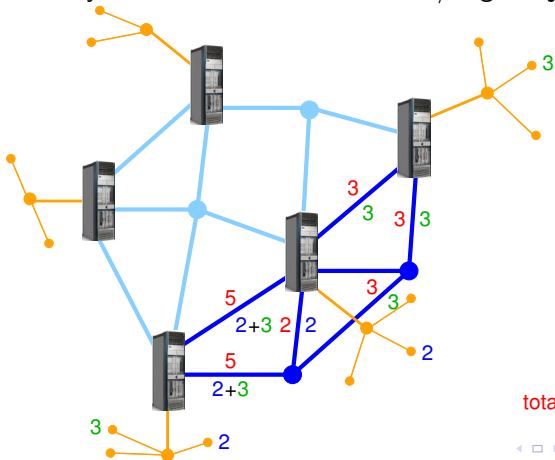
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* for node-disjointness

The End

TO BE CONTINUED WITH
EXERCISES AT 2PM!

The End

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ENJOY LUNCH!