

Line Planning in Public Transport

CO@Work Berlin

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DFG Research Center MATHEON
Mathematics for key technologies



Introduction

Line Planning with Fixed Passenger Routes

A Column Generation Approach to Line Planning

Line Planning in Practice

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Line Planning in Practice

Planning Steps in Public Transport

network design



line planning



timetabling

Linie	Anzahl	Strecken	Stellen
1. S-Bahn	12.10	12.10	12.10
2. S-Bahn	12.10	12.10	12.10
3. S-Bahn	12.10	12.10	12.10
4. S-Bahn	12.10	12.10	12.10
5. S-Bahn	12.10	12.10	12.10
6. S-Bahn	12.10	12.10	12.10
7. S-Bahn	12.10	12.10	12.10
8. S-Bahn	12.10	12.10	12.10
9. S-Bahn	12.10	12.10	12.10
10. S-Bahn	12.10	12.10	12.10
11. S-Bahn	12.10	12.10	12.10
12. S-Bahn	12.10	12.10	12.10
13. S-Bahn	12.10	12.10	12.10
14. S-Bahn	12.10	12.10	12.10
15. S-Bahn	12.10	12.10	12.10
16. S-Bahn	12.10	12.10	12.10
17. S-Bahn	12.10	12.10	12.10
18. S-Bahn	12.10	12.10	12.10
19. S-Bahn	12.10	12.10	12.10
20. S-Bahn	12.10	12.10	12.10

fare planning

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6. S-Bahn	12.10	12.10	12.10
7. S-Bahn	12.10	12.10	12.10
8. S-Bahn	12.10	12.10	12.10
9. S-Bahn	12.10	12.10	12.10
10. S-Bahn	12.10	12.10	12.10
11. S-Bahn	12.10	12.10	12.10
12. S-Bahn	12.10	12.10	12.10
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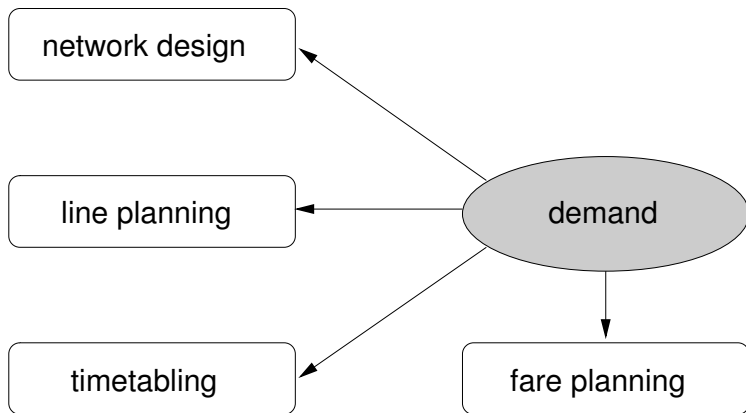


duty scheduling



vehicle scheduling





Data acquisition

- ▶ passenger interviews (purpose of trip, start and end,...)
- ▶ automatic counting in vehicles
→ reflects aggregated passenger demand of *current* transportation system

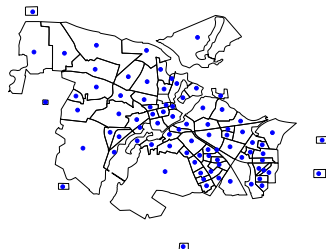
Data representation

- ▶ Origin Destination Matrix (OD Matrix)
- ▶ passenger volume for each edge

There are statistical and mathematical programming methods for estimating OD matrices from edge counts.

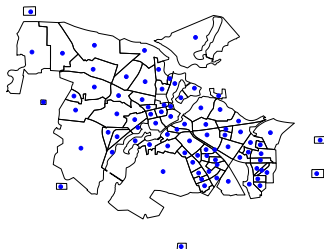
OD Matrix

- ▶ public transport area divided into different districts
- ▶ district represented by OD node
- ▶ OD Matrix – number of passengers traveling between each two OD nodes



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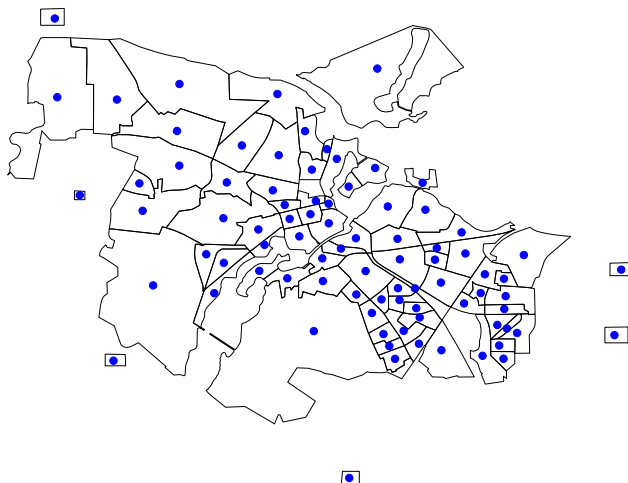
Features

- ▶ aggregated (usually given for a whole day)
- ▶ give snapshot type of view
- ▶ representation of reality questionable
- ▶ industry standard for estimating transportation demand
- ▶ no relevant alternative in sight

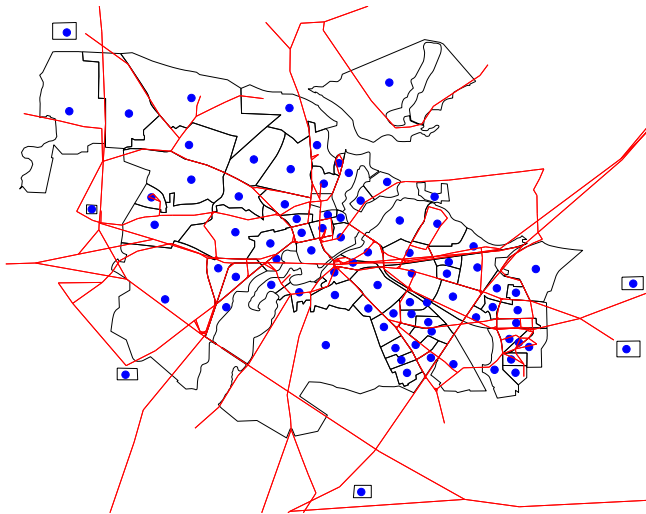
OD Matrix – Potsdam



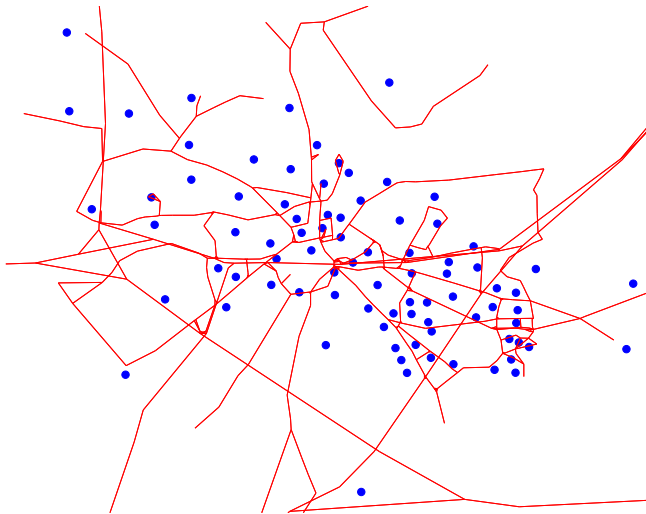
Traffic Area Divided in Districts (OD-Nodes)



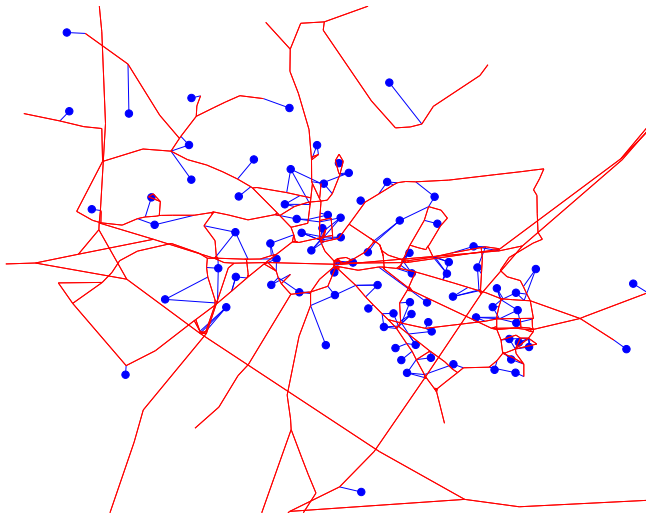
OD-Nodes, Districts, and Network



OD-Nodes and Network



OD-Nodes and Connection to Network



Line Planning Problem (LPP)

Given:

- ▶ network
- ▶ demands d_{st} (OD-matrix)
- ▶ operating costs and traveling times

Line: path (list of stations) with special start and end nodes, frequency

Problem: Design lines to satisfy demand.

Goals:

- ▶ minimize traveling times or number of transfers
- ▶ minimize costs of line plan

Heuristics:

- ▶ Build lines from smaller pieces
Remove lines from a “complete” line plan:
Patz, 1925
Lampkin and Saalmans 1967;
Dubois, Bel, and Llibre 1979;
Sonntag 1979
- ▶ Enumeration of lines:
Ceder and Wilson 1986
- ▶ Local search:
Mandl 1980
- ▶ Quadratic covering model:
Ceder and Israeli 1992, 1995

Mixed integer programming methods:

► Fixed Passenger Routes – System Split

(for rail transport)

► Minimize cost:

Claessens, van Dijk, and Zwaneveld 1995;
Goossens, van Hoesel, and Kroon 2001, 2002;
Bussieck, Lindner, and Lübbecke 2002

► Maximize direct travelers:

Bouma, Oltrogge 1994;
Bussieck, Kreuzer, and Zimmermann 1997

► Free Routing of Passengers

► Minimize transfers/transfer time:

Scholl 2005;
Schöbel and Scholl 2005

► Minimize travel time and cost (weighted sum):

Borndörfer, Grötschel, Pfetsch, 2005, 2007

Bouma and Oltrogge 1994

Idea: Split network into different means of transport (fast train, local train; bus, tram, subway)

~> find line plan for each network, independently

Assumptions on behavior of passengers:

- ▶ “choose shortest path”,
- ▶ “change to faster system as early as possible”,
- ▶ “change to slower system as late as possible”.

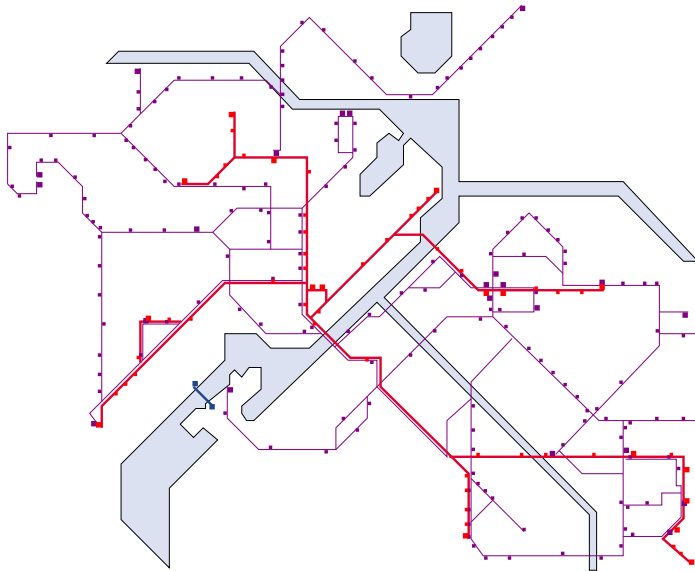
~> distribution of passengers to different paths

~> passenger traveling paths are known

Notation for line planning problems (LPP)

- ▶ number M of transportation modes (bus, tram, subway,...)
- ▶ undirected multigraph $G = (V, E) = (V, E_1 \cup, \dots, \cup, E_M)$
- ▶ terminals: set of nodes $\mathcal{T}_1, \dots, \mathcal{T}_M$ where lines can start and end
- ▶ OD matrix $d_{st} \in \mathbb{Q}_+^{V \times V}$
- ▶ $D = \{(s, t) \in V \times V \mid d_{st} > 0\}$ set of OD pairs
- ▶ \mathcal{L} set of lines (simple paths)
- ▶ \mathcal{F}_ℓ set of frequencies for each line

Potsdam Network



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Line Planning with System Split

Assumptions

- ▶ number of passengers ρ_e for each edge known
- ▶ only one mode given, i.e., capacity for all lines equal
- ▶ \mathcal{L} pool of predefined lines

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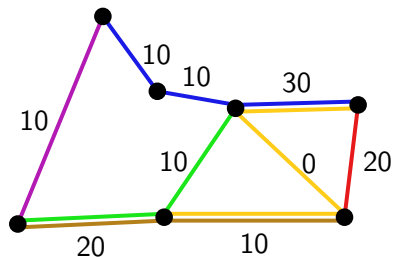
Definition Let

- ▶ $G = (V, E)$ be a public transportation graph,
- ▶ \mathcal{L} a set of simple line paths in G with capacity K
- ▶ \mathcal{F} a set of possible frequencies
- ▶ ρ_e transportation demand for each edge $e \in E$.

The *Feasible Line Plan Problem* is to find a set of lines $\mathcal{L}' \subseteq \mathcal{L}$ and frequencies $f_\ell \in \mathcal{F}$ for all $\ell \in \mathcal{L}'$ such that

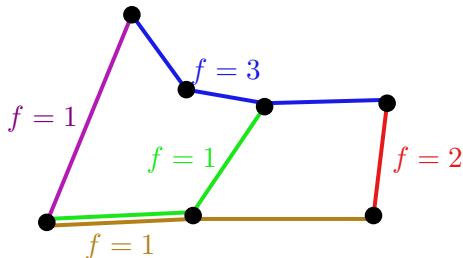
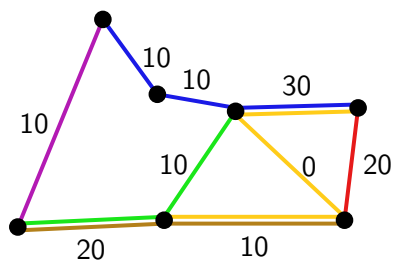
$$\sum_{\ell \in \mathcal{L}', e \in \ell} K \cdot f_\ell \geq \rho_e \quad \forall e \in E.$$

Example



- ▶ public transport network with given demand on edges
- ▶ capacity of a line $K = 10$
- ▶ possible frequencies $\mathcal{F} = \{1, 2, 3\}$

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Subproblem: Minimum Line Cover

Definition

Given

- ▶ a public transportation graph $G = (V, E)$,
- ▶ a set of simple paths \mathcal{L} defined in G ,
- ▶ and a set of edges $E' \subseteq E$ with positive transportation demand.

The *Minimum Line Cover Problem* is to find a minimum set of lines $\mathcal{L}' \subseteq \mathcal{L}$ that cover all “demand edges” E' .

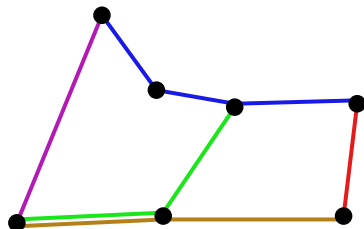
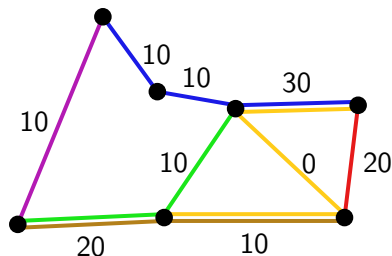
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Subproblem: Minimum Line Cover

The minimum line cover problem can be formulated as a set covering problem.

$$\begin{array}{ll} \min & \sum_{\ell \in \mathcal{L}} x_{\ell} \\ \text{s.t.} & \sum_{\ell: e \in \ell} x_{\ell} \geq 1 \quad \forall e \in E' \\ & x_{\ell} \in [0, 1] \quad \forall \ell \in \mathcal{L} \end{array}$$

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Proposition

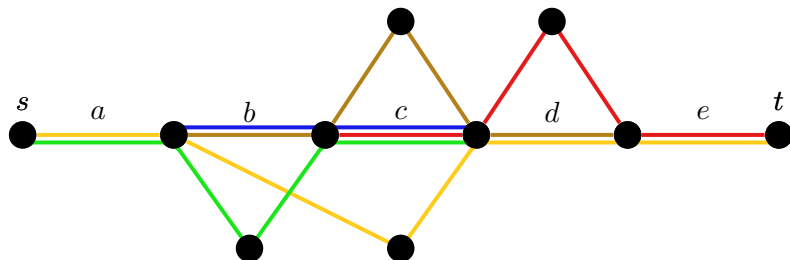
The minimum line cover problem is NP-hard.

Proof: Reduction from set covering problem.

$$S = \{a, b, c, d, e\}, \quad (\{a, c\}, \{b, d\}, \{b, c\}, \{c, e\}, \{a, d, e\})$$

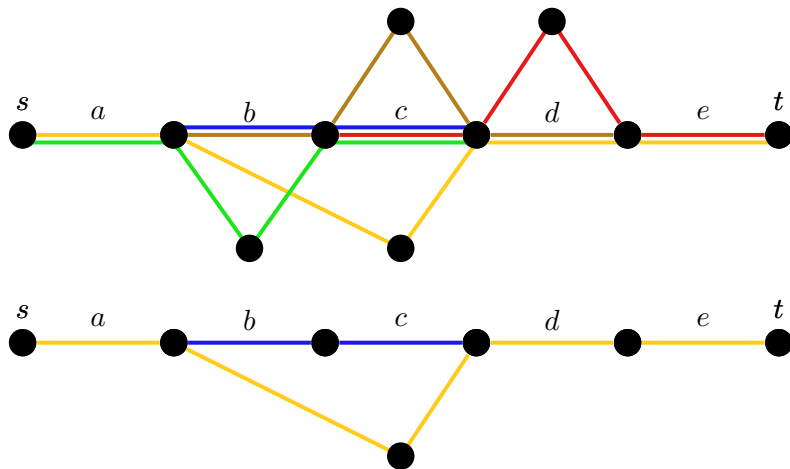
Complexity – Proof (Idea: Schöbel, Scholl, 2005)

$$S = \{a, b, c, d, e\}, \quad (\{a, c\}, \{b, d\}, \{b, c\}, \{c, e\}, \{a, d, e\})$$



Complexity – Proof (Idea: Schöbel, Scholl, 2005)

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Cost Minimization Model (Claessens et al.)

$$\begin{aligned} \min \quad & \sum_{\ell \in \mathcal{L}} \left\lceil \frac{f_{\ell} T_{\ell}}{T} \right\rceil (C^t + C^c z_{\ell}) + d_{\ell} f_{\ell} (c^t + c^c z_{\ell}) \\ \text{s.t.} \quad & \underline{\Lambda}_e \leq \sum_{\ell \in \mathcal{L}_e} f_{\ell} \leq \overline{\Lambda}_e & \forall e \in E \\ & \sum_{\ell \in \mathcal{L}_e} K f_{\ell} z_{\ell} \geq \rho_e & \forall e \in E \\ & \underline{z} \leq z_{\ell} \leq \overline{z} & \forall \ell \in \mathcal{L} \\ & f_{\ell}, z_{\ell} \in \mathbb{Z}_+ & \forall \ell \in \mathcal{L} \end{aligned}$$

Variables: z_{ℓ} number of carriages of line ℓ
 f_{ℓ} frequency of line ℓ

Parameter: K capacity of one carriage
 $\underline{\Lambda}_e, \overline{\Lambda}_e$ lower, upper bound on frequency ($\underline{\Lambda}_e = \lceil \frac{\rho_e}{\underline{z} \cdot K} \rceil$)
 $\underline{z}, \overline{z}$ lower, upper bound on number of carriages

Objective Function

$$\underbrace{\left\lceil \frac{f_\ell T_\ell}{T} \right\rceil}_{\# \text{ trains}} \underbrace{(C^t + C^c z_\ell)}_{\text{fixed costs}} + \underbrace{d_\ell f_\ell (c^t + c^c z_\ell)}_{\text{operating costs}}$$

Parameter: T time horizon
 T_ℓ turn around time for line ℓ

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 C^t fixed cost for one train
 C^c fixed cost for one carriage

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- Parameter:
- T time horizon
 - T_ℓ turn around time for line ℓ
 - C^t fixed cost for one train
 - C^c fixed cost for one carriage
 - d_ℓ length of line ℓ
 - c^t operating cost for one train per distance
 - c^c operating cost for one carriage per distance

Cost Minimization Model

$$\min \sum_{\ell \in \mathcal{L}} \left\lceil \frac{f_{\ell} T_{\ell}}{T} \right\rceil (C^t + C^c z_{\ell}) + d_{\ell} f_{\ell} (c^t + c^c z_{\ell})$$

$$s.t. \quad \underline{\Lambda}_e \leq \sum_{\ell \in \mathcal{L}_e} f_{\ell} \leq \overline{\Lambda}_e \quad \forall e \in E$$

$$\sum_{\ell \in \mathcal{L}_e} K f_{\ell} z_{\ell} \geq \rho_e \quad \forall e \in E$$

$$\underline{z} \leq z_{\ell} \leq \overline{z} \quad \forall \ell \in \mathcal{L}$$

$$f_{\ell}, z_{\ell} \in \mathbb{Z}_+ \quad \forall \ell \in \mathcal{L}$$

Cost Minimization Model

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Linearization

- ▶ \mathcal{F} set of feasible frequencies, e.g., $\mathcal{F} = \{1, \dots, F\}$
- ▶ \mathcal{C} set of feasible numbers of carriages, e.g., $\mathcal{C} = \{3, 4, 5\}$
- ▶ $\mathcal{R} = \mathcal{L} \times \mathcal{F} \times \mathcal{C}$

$$\begin{aligned}
 \min \quad & \sum_{r \in \mathcal{R}} \left(\left\lceil \frac{f_{r_\ell} T_{r_\ell}}{T} \right\rceil (C^t + C^c r_z) + d_{r_\ell} r_f (c^t + c^c r_z) \right) \cdot y_r \\
 \text{s.t.} \quad & \underline{\Lambda}_e \leq \sum_{r \in \mathcal{R}: e \in r_\ell} r_f y_r \leq \bar{\Lambda}_e & \forall e \in E \\
 & \sum_{r \in \mathcal{R}: e \in r_\ell} K r_f r_z y_r \geq \rho_e & \forall e \in E \\
 & \sum_{r \in \mathcal{R}: r_\ell = \ell} y_r \leq 1 & \forall \ell \in \mathcal{L} \\
 & y_r \in \{0, 1\} & \forall r \in \mathcal{R}
 \end{aligned}$$

Variables: y_r choosing combination of $r = (r_\ell, r_f, r_z) \in \mathcal{R}$
(line frequency and number of carriage)

Solving with preprocessing and branch-and-cut methods.

Proposition

The cost minimizing line planning approach is NP-hard.

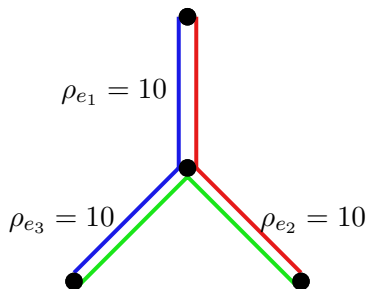
Proof.

Setting

- ▶ $\underline{z} = \bar{z}$, (i.e., fixed number of carriages),
- ▶ $F = 1$, (i.e., fixed frequency),
- ▶ $K = \max\{\rho_e \mid e \in E\}$,
- ▶ $\underline{\Lambda}_e = 1, \bar{\Lambda}_e = \infty$
- ▶ $C^t = 1, C^c = c^c = c^t = 0$

leads to a minimum line cover problem. □

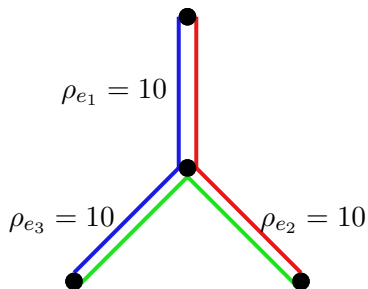
Cutting Plane – Example



- ▶ $\mathcal{F} = \mathcal{C} = \{1\}$, $\mathcal{L} = \{1, 2, 3\}$, $K = 10$
- ▶ consider capacity constraint

$$\sum_{r \in \mathcal{R}: e \in r_\ell} K r_f r_z y_r \geq \rho_e \quad \forall e$$

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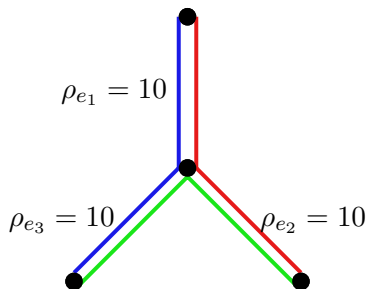
$$\sum_{r \in \mathcal{R}: e \in r_\ell} K r_f r_z y_r \geq \rho_e \quad \forall e$$

$$10 \cdot y_1 + 10 \cdot y_2 \geq 10 \quad \{e_1\}$$

$$10 \cdot y_1 + 10 \cdot y_3 \geq 10 \quad \{e_2\}$$

$$10 \cdot y_2 + 10 \cdot y_3 \geq 10 \quad \{e_3\}$$

Cutting Plane – Example



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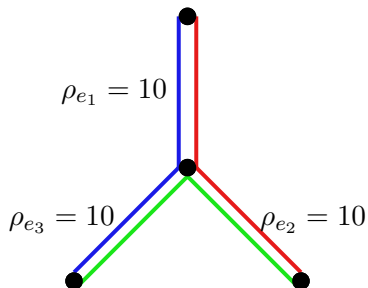
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$$10 \cdot y_2 + 10 \cdot y_3 \geq 10 \quad \{e_3\}$$

- ▶ $y_1 = y_2 = y_3 = 0.5$ is solution
- ▶ $\rightsquigarrow y_1 + y_2 + y_3 \geq 2$ valid

Cutting Plane – Example



Proposition

Let

- ▶ $E' \subseteq E$ such that $\rho_e > 0 \ \forall e \in E'$,
- ▶ $\alpha_{E'}^\ell := |\ell \cap E'|$, and
- ▶ $\alpha_{E'}^{\max} := \max\{\alpha_{E'}^\ell \mid \ell \in \mathcal{L}\}$.

Then

$$\sum_{r \in \mathcal{R}, \alpha_{E'}^{r\ell} \geq 1} y_r \geq \left\lceil \frac{|E'|}{\alpha_{E'}^{\max}} \right\rceil$$

is a valid inequality.

Discussion of the Model

- ▶ detailed cost function
based on following assumption
 - ▶ no switching of rolling stock between lines
 - ▶ line is operated by same trains (same number of carriages)
 - ▶ timetable is periodic (e.g. repeated every hour)
- ▶ many variables
(every possible combination of frequency and number of carriages)
however, reduction by preprocessing
- ▶ only one transportation mode considered
- ▶ passenger paths are fixed
- ▶ line pool

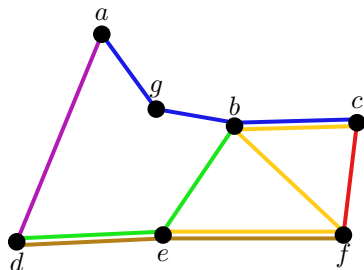
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Example – Free Passenger Routing



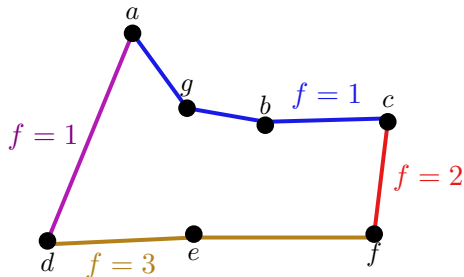
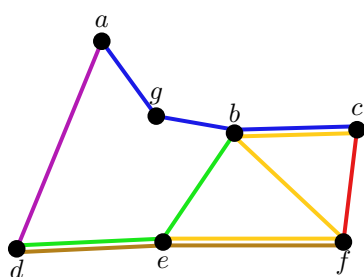
- ▶ public transport network with following demand (OD pairs):

- ▶ $a \rightarrow c$: 10
- ▶ $a \rightarrow d$: 10
- ▶ $d \rightarrow c$: 10
- ▶ $c \rightarrow f$: 20
- ▶ $d \rightarrow f$: 20

	a	c	d	f
a	0	10	10	0
c	0	0	0	20
d	0	10	0	20
f	0	0	0	0

- ▶ capacity of a line $K = 10$, frequencies $\mathcal{F} = \{1, 2, 3\}$

Example – Free Passenger Routing



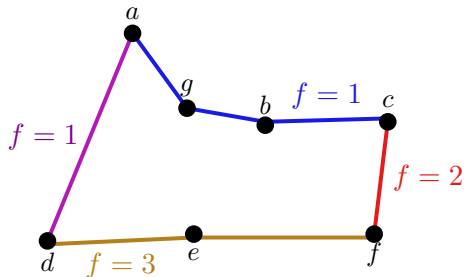
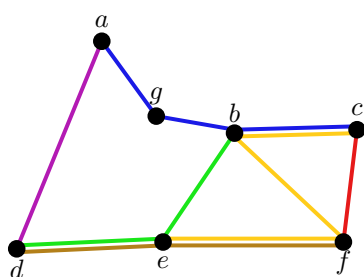
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- capacity of a line $K = 10$, frequencies $\mathcal{F} = \{1, 2, 3\}$
- \rightsquigarrow directed graph $G = (V, A)$ for passenger paths

Multi Commodity Flow Model (Grötschel, Borndörfer, Pfetsch)

$$\min \quad \lambda \sum_{\ell} (C_{\ell} x_{\ell} + c_{\ell} f_{\ell}) + (1 - \lambda) \sum_p \tau_p y_p$$

$$\text{i)} \quad \sum_{p \in \mathcal{P}_{st}} y_p = d_{st} \quad \forall (s, t) \in D \quad \text{transport all passengers}$$

$$\text{ii)} \quad \sum_{p \ni a} y_p \leq \sum_{\ell: e(a) \in \ell} \kappa_{\ell} f_{\ell} \quad \forall a \in A \quad \text{arc capacity constraints}$$

$$\text{iii)} \quad \sum_{\ell \ni e} f_{\ell} \leq \Lambda_e \quad \forall e \in E \quad \text{frequency bounds}$$

$$\text{iv)} \quad f_{\ell} \leq F x_{\ell} \quad \forall \ell \in \mathcal{L} \quad \text{coupling constraints}$$

$$y_p \in \mathbb{R}_+ \quad \forall p \in \mathcal{P} \quad \text{passenger flow}$$

$$x_{\ell} \in \{0, 1\} \quad \forall \ell \in \mathcal{L} \quad \text{choose line } \ell$$

$$f_{\ell} \in \mathbb{R}_+ \quad \forall \ell \in \mathcal{L} \quad \text{frequency of line } \ell$$

Discussion of the Model

Properties of the model:

- ▶ no system split
- ▶ continuous frequencies
- ▶ other linear constraints possible
- ▶ system optimum = user equilibrium

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- ▶ Lines can be generated dynamically (column generation).

Disadvantages of the model:

- ▶ Some passengers may use long paths.
possible solution: length constraints
- ▶ Transfers between lines of same type cannot be controlled.

Transfers

Lines of different type:

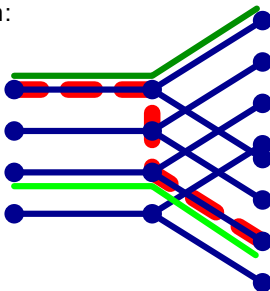
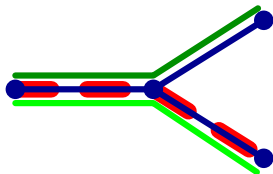
Time penalties for transfers

Lines of same type:

Capacity constraints do not distinguish between these lines:

$$\sum_{p \ni a} y_p \leq \sum_{\ell: e(a) \in \ell} \sum_{f \in \mathcal{F}_\ell} \kappa_\ell^f x_\ell^f$$

Solution: expansion of the graph:



Problem: Symmetries

$$\begin{aligned}
 \min \quad & \sum_{\ell \in \mathcal{L}} (C_\ell x_\ell + c_\ell f_\ell) + \sum_{p \in \mathcal{P}} \tau_p y_p \\
 \text{s.t.} \quad & \sum_{p \in \mathcal{P}_{st}} y_p = d_{st} & \forall (s, t) \in D \\
 & \sum_{p: a \in p} y_p \leq \sum_{\ell: e(a) \in \ell} \kappa_\ell f_\ell & \forall a \in A \\
 & \sum_{\ell: e \in \ell} f_\ell \leq \Lambda_e & \forall e \in E \\
 & f_\ell \leq F x_\ell & \forall \ell \in \mathcal{L} \\
 & x_\ell \in [0, 1] & \forall \ell \in \mathcal{L} \\
 & f_\ell \geq 0 & \forall \ell \in \mathcal{L} \\
 & y_p \geq 0 & \forall p \in \mathcal{P}.
 \end{aligned}$$

$$\begin{aligned} \text{(LP)} \quad & \min \quad \sum_{\ell \in \mathcal{L}} \gamma_{\ell} f_{\ell} + \sum_{p \in \mathcal{P}} \tau_p y_p \\ \text{s.t.} \quad & \sum_{p \in \mathcal{P}_{st}} y_p = d_{st} \quad \forall (s, t) \in D \\ & \sum_{p: a \in p} y_p - \sum_{\ell: e(a) \in \ell} \kappa_{\ell} f_{\ell} \leq 0 \quad \forall a \in A \\ & \sum_{\ell: e \in \ell} f_{\ell} \leq \Lambda_e \quad \forall e \in E \\ & f_{\ell} \geq 0 \quad \forall \ell \in \mathcal{L} \\ & y_p \geq 0 \quad \forall p \in \mathcal{P}. \end{aligned}$$

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Solve LP relaxation with column generation.

Proposition

The computation of the optimal value of (LP) is NP-hard.

Pricing of Passenger Paths

The dual model is:

$$\begin{aligned} \text{(DLP)} \quad & \min \quad \sum_{(s,t) \in D} d_{st} \pi_{st} - \sum_{e \in E} \Lambda_e \eta_e \\ \text{s.t.} \quad & \pi_{st} - \sum_{a \in p} \mu_a \leq \tau_p \quad \forall p \in \mathcal{P}_{st}, (s,t) \in D \\ & \sum_{e \in \ell} (\kappa_\ell (\mu_{a(e)} + \mu_{\bar{a}(e)}) - \eta_e) \leq \gamma_\ell \quad \forall \ell \in \mathcal{L} \\ & \eta_e \geq 0 \quad \forall e \in E \\ & \mu_a \geq 0 \quad \forall a \in A \end{aligned}$$

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$$\begin{aligned} \bar{\tau}_p &= \tau_p - \pi_{st} + \sum_{a \in p} \mu_a = -\pi_{st} + \sum_{a \in p} (\mu_a + \tau_a) \\ \bar{\tau}_p < 0 &\Leftrightarrow \sum_{a \in p} (\mu_a + \tau_a) < \pi_{st} \end{aligned}$$

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\rightsquigarrow shortest path problem

Pricing of Line Paths

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Pricing of Line Paths

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\rightsquigarrow longest path problem (NP-hard)

Pricing of Line Paths

Let n be the number of nodes.

Theorem

If the lengths of paths are $O(\log n)$, one can solve the longest path problem in polynomial time.

Corollary

If the lengths of lines are $O(\log n)$, one can solve the LP relaxation in polynomial time.


Alternative method: Find lines by *enumeration*.

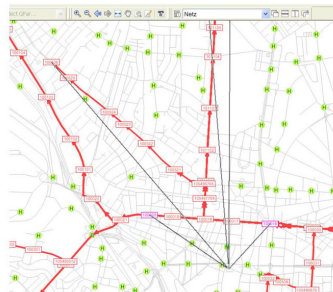
Introduction

Line Planning with Fixed Passenger Routes

A Column Generation Approach to Line Planning

Line Planning in Practice

- ▶ sophisticated simulation tools,
e.g., VISUM 
(but no mathematical optimization methods)
- ▶ experience of practitioners
- ▶ political requirements



Cooperation with: ViP Potsdam



network of Potsdam:

inhabitants:	150,000
travels in morning traffic:	42 973
number of bus lines:	15 + 8
number of tram lines:	6
nodes: 872 (1643)	edges: 2462 (5470)
OD-nodes: 385	nonzeros: 12 787

Variation of (Grötschel, Borndörfer, Pfetsch)

$$\min \quad \lambda \sum_{\ell \in \mathcal{L}} \sum_{f \in F} c_{\ell}^f x_{\ell}^f + (1 - \lambda) \sum_{p \in \mathcal{P}} \tau_p y_p$$

$$\text{i)} \quad \sum_{p \in \mathcal{P}_{st}} y_p = d_{st} \quad \forall (s, t) \in D \quad \text{transport all passengers}$$

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$$\text{iii)} \quad \sum_{f \in \mathcal{F}_{\ell}} x_{\ell}^f \leq 1 \quad \forall \ell \in \mathcal{L} \quad \text{one frequency per line}$$

$$y_p \in \mathbb{R}_+ \quad \forall p \in \mathcal{P} \quad \text{passenger flow}$$

$$x_{\ell}^f \in \{0, 1\} \quad \forall \ell \in \mathcal{L} \quad \text{line and frequency}$$

- ▶ pricing problem for passenger paths similar as before
- ▶ pricing of line paths? (exercise)

Things to Do Besides Optimization

How to present the solution?

Things to Do Besides Optimization

How to present the solution?

- ▶ list of lines with stations and frequencies, basic visualization

Solution – List

line name cycle time in minutes:

BVB134R;32088;U 30
BVB234H;10723;U 30
BVB534R;35166;U 30
HVG612;180287;U 30
N01RB20H;612362;U 60
N01RB21R;610169;U 60
VIB692H;530239;U 30
VIT92;92_KA-MJ;U 20

list of stations for each line:

BVB134R;32088;U Hottengrund (Berlin)
BVB134R;32088;U Kaserne Hottengrund (Berlin)
BVB134R;32088;U Temmeweg (Berlin)
BVB134R;32088;U Göswensteiner Gang (Berlin)
BVB134R;32088;U Parnemannweg (Berlin)
BVB134R;32088;U Alt-Kladow (Berlin)
BVB134R;32088;U Finnenhaus-Siedlung (Berlin)
BVB134R;32088;U Neukladower Allee (Berlin)
BVB134R;32088;U Krankenhaus Havelhöhe (Berlin)
BVB134R;32088;U General-Steinhoff-Kaserne (Berlin)
BVB134R;32088;U Weg nach Breitehorn (Berlin)
BVB134R;32088;U Breitehornweg (Berlin)
BVB134R;32088;U Helleberge (Berlin)
BVB134R;32088;U Am Graben (Berlin)
BVB134R;32088;U Alt-Gatow (Berlin)
BVB134R;32088;U Gatow Kirche (Berlin)
BVB134R;32088;U Pfirsichweg (Berlin)
BVB134R;32088;U Emil-Basdeck-Str. (Berlin)
BVB134R;32088;U Biberburg (Berlin)
BVB134R;32088;U Zur Haveldüne (Berlin)
BVB134R;32088;U Gatower Str./Weinmeisterhornweg (Berlin)
BVB134R;32088;U Sandheideweg (Berlin)

Basic Visualization



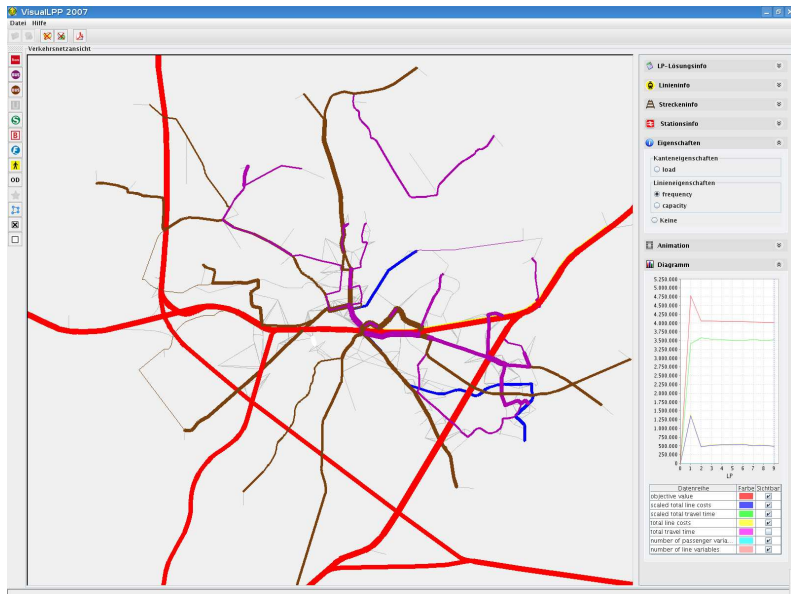
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VisualLPP (M. Kinder)



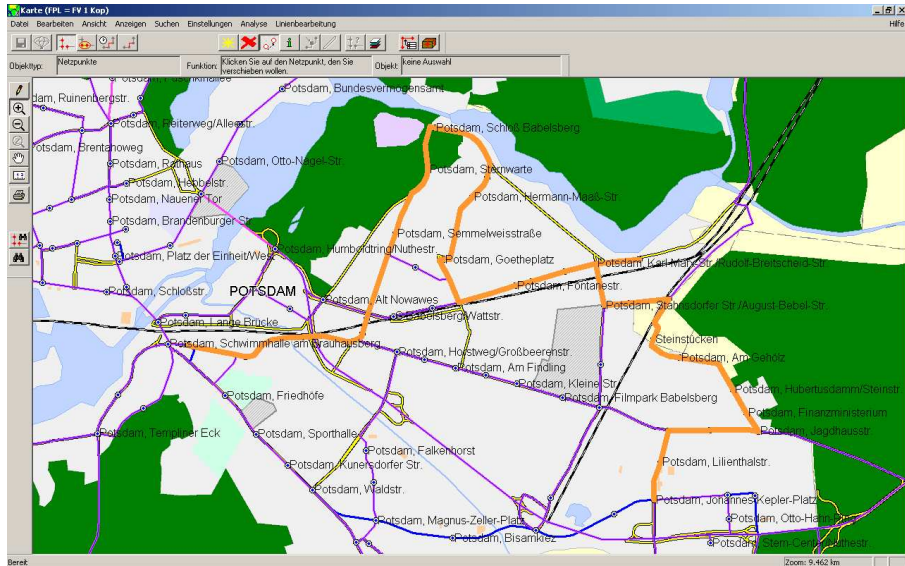
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Map



Things to do besides Optimization

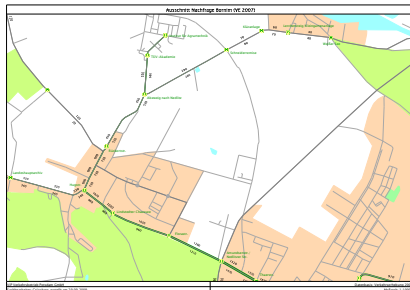
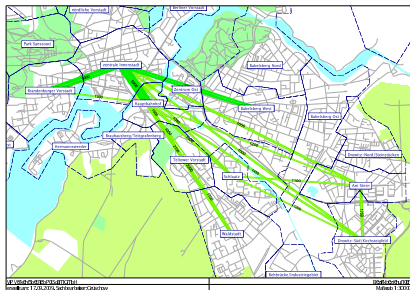
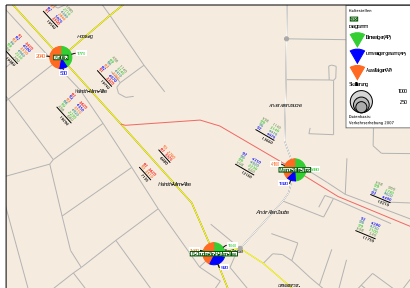
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- ▶ visualization with map
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 disadvantage: restricted evaluation of solution
- ▶ visualization with VISUM
 advantage: geographic map, evaluation of solution possible
 disadvantage: expensive



Other Things to Do

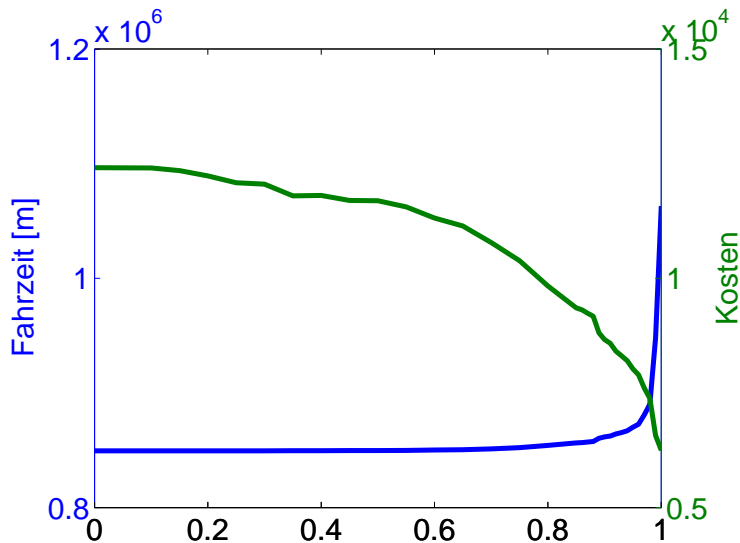
Data

- ▶ some data missing, incomplete, contains errors
 \rightsquigarrow long iterative process to get needed data

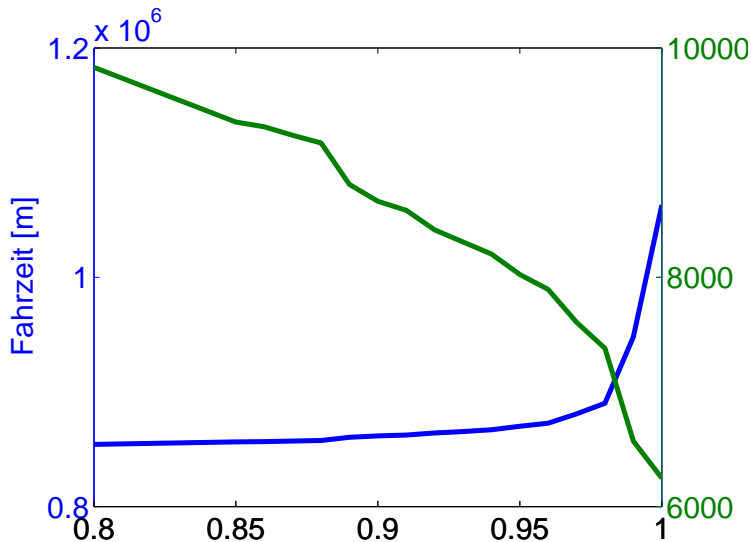
Parameter

- ▶ cost function, operating cost for each line
- ▶ capacities of lines
- ▶ choose terminal nodes (endpoint of line)
- ▶ weighting of cost and travel time (choosing λ)
 \rightsquigarrow computation of Pareto curve

Pareto Curve



Pareto Curve



column generation of passenger paths, predefined line pool
(computations in chronological order):

Instance	$ \mathcal{L} $	$ \mathcal{F} $	#line var	#constr.	time ¹
potsdam1	30 232	4	120 592	44 577	349
potsdam2	29 142	2	58 268	43 419	125
potsdam3	1172	3	3 486	15 491	24
potsdam4	623	3	1 755	14 939	20
potsdam5	3861	3	11 471	21 199	377 ²

¹in minutes, after solving root node including separators and heuristics; gap < 5%

²for adjusted network

General Problems

- ▶ data contains information relevant for transportation company but not relevant for optimization tools
(e.g., nodes of network not only stops but also crossings, track switches, turnouts,..)

Problems concerning our solutions

- ▶ too many too short lines
- ▶ service (frequency) on some stations too small
- ▶ the importance of tram not represented by our solution
(important for tourism, environment, prestige)
- ▶ lines over a train crossing – no robust timetable
- ▶ “curious” bus lines (no stations shared with tram, regional traffic)

- ▶ relevant vs. irrelevant data

Problems – Solutions

- ▶ relevant vs. irrelevant data
 \rightsquigarrow preprocessing
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 Idea: condition of covering all tracks of tram
- ▶ lines over train crossing
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- ▶ “curious” bus lines (no stations shared with tram, regional traffic)
 Idea: generate only bus lines that contain a station shared with tram or regional traffic

Work in Progress...

Work in Progress...

- ▶ first step to establish optimization methods for line planning in practice
- ▶ line planning optimization not completely solved
- ▶ hope for future: optimization in (service design of) public transport as decision support

Line Planning in Public Transport

CO@Work Berlin

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10/02/2009



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DFG Research Center MATHEON
Mathematics for key technologies

